

# Witnesses For Vector Addition Systems

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# Vector Addition Systems

## Definition

A vector addition system (VAS) is a finite set  $\mathbf{A} \subseteq \mathbb{Z}^d$ .

$$\begin{array}{ccc} & \mathbf{A} & \\ & \cup & \\ & \mathbf{a} & \\ \mathbf{x} & \longrightarrow & \mathbf{y} \iff \mathbf{x} + \mathbf{a} = \mathbf{y} \\ \cap & & \cap \\ \mathbb{N}^d & & \mathbb{N}^d \end{array}$$

# Central Model

VAS natural model:

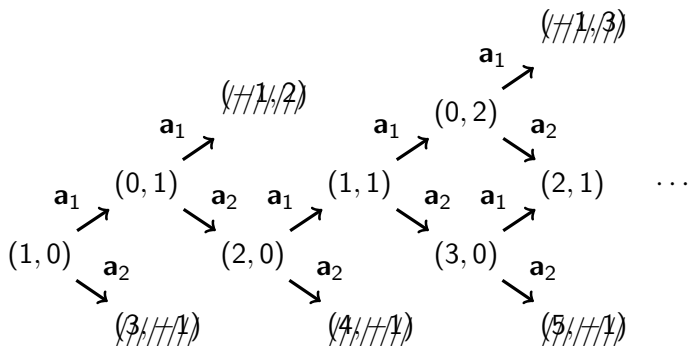
- Concurrent systems.
- Parametrized systems.
- Energy Games.
- Encoding satisfiability problems for data logics.

Equivalent to other models:

- Petri nets.
- Petri nets with states.
- Vector addition systems with states.
- Minsky machines without zero test.

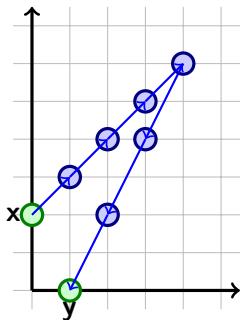
# Reachability Graph View Point

$\mathbf{A} = \{\mathbf{a}_1, \mathbf{a}_2\}$  with  $\mathbf{a}_1 = (-1, 1)$  and  $\mathbf{a}_2 = (2, -1)$



# Geometrical View Point

$$\mathbf{A} = \left\{ \begin{array}{c} \nearrow \\ \searrow \end{array} \right\}$$



# Decidability

Decidable problems:

- Termination.
- Boundedness.
- Coverability.
- Reachability.

Open problems:

- Semilinearity.
- Homestate.

Undecidable problems:

- Reachability set equality.
- CTL model checking.
- Many games.

# Decidability by RECORE

A problem that is recursively enumerable and co recursively enumerable is decidable.

⇒ A problem is decidable if there exist:

- checkable witnesses when the property hold.
- checkable witnesses when the property does not hold.

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# Coverability Problem

A final configuration  $\mathbf{c}_{\text{final}}$  is coverable from an initial configuration  $\mathbf{c}_{\text{init}}$  by a VAS  $\mathbf{A}$  if:

$$\mathbf{c}_{\text{init}} \xrightarrow{\mathbf{A}^*} (\mathbf{c}_{\text{final}} + \mathbb{N}^d)$$

## Definition (Coverability problem)

Deciding if  $\mathbf{c}_{\text{final}}$  is coverable from  $\mathbf{c}_{\text{init}}$  for a VAS  $\mathbf{A}$ .

Application: Safety properties [mutual exclusion]

## Definition (Coverability Witnesses)

A word  $w \in \mathbf{A}^*$  and a configuration  $\mathbf{e} \in \mathbb{N}^d$  such that:

$$\mathbf{c}_{\text{init}} \xrightarrow{w} (\mathbf{c}_{\text{final}} + \mathbf{e})$$

Worst case  $|w|$  doubly exponentially long.

The coverability problem is EXPSPACE-complete.

[C. Rachoff:TCS'78].

[E. Cardoza, R. J. Lipton, A. R. Meyer:STOC'76].

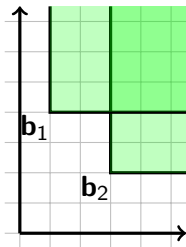
## Definition (Uncoverability Witnesses)

A finite set  $\mathbf{B} \subseteq \mathbb{N}^d$  denoting a set  $\mathbf{C} = \bigcup_{\mathbf{b} \in \mathbf{B}} \mathbf{b} + \mathbb{N}^d$  such that:

- For every  $\mathbf{x} \xrightarrow{\mathbf{a}} \mathbf{y}$  we have:

$$\mathbf{y} \in \mathbf{C} \Rightarrow \mathbf{x} \in \mathbf{C}$$

- $\mathbf{c}_{\text{init}} \notin \mathbf{C}$
- $\mathbf{c}_{\text{final}} \in \mathbf{C}$



Let:

$$\mathbf{C} = \left\{ \mathbf{c} \in \mathbb{N}^d \mid \mathbf{c} \xrightarrow{\mathbf{A}^*} (\mathbf{c}_{\text{final}} + \mathbb{N}^d) \right\}$$

$$\mathbf{B} = \min_{\leq}(\mathbf{C})$$

Just observe that  $\mathbf{C} = \bigcup_{\mathbf{b} \in \mathbf{B}} \mathbf{b} + \mathbb{N}^d$ .

$\mathbf{C}$  is computable with a backward algorithm in at most a double exponential number of iterations with  $\mathbf{C}_0 = \mathbf{c}_{\text{final}} + \mathbb{N}^d$  and:

$$\mathbf{C}_{n+1} = \left\{ \mathbf{c} \in \mathbb{N}^d \mid \mathbf{c} \xrightarrow{\mathbf{A}} \mathbf{C}_n \right\}$$

[L. Bozzelli, P. Ganty:RP'11]

[R. Lazic, S. Schmitz:RP'15]

# Reachability Problem

A final configuration  $\mathbf{c}_{\text{final}}$  is reachable from an initial configuration  $\mathbf{c}_{\text{init}}$  by a VAS  $\mathbf{A}$  if:

$$\mathbf{c}_{\text{init}} \xrightarrow{\mathbf{A}^*} \mathbf{c}_{\text{final}}$$

## Definition (Reachability problem)

Deciding if  $\mathbf{c}_{\text{final}}$  is reachable from  $\mathbf{c}_{\text{init}}$  for a VAS  $\mathbf{A}$ .

Application:

- More general safety properties.
- Inclusion of Petri nets/ VASes languages.

[M. Heizmann, J. Hoenicke, A. Podelski:CAV'12]

## Definition (Reachability Witnesses)

A word  $w \in \mathbf{A}^*$  such that:

$$\mathbf{c}_{\text{init}} \xrightarrow{w} \mathbf{c}_{\text{final}}$$

$|w|$  is bounded by  $O(F_{\omega^3})$ .

[J. Leroux, S. Schmitz:LICS'15]

## Definition (Unreachability Witnesses)

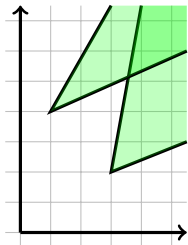
A Presburger formula  $\phi$  denoting a set  $\mathbf{C} \subseteq \mathbb{N}^d$  such that:

- For every  $\mathbf{x} \xrightarrow{\mathbf{a}} \mathbf{y}$  we have:

$$\mathbf{y} \in \mathbf{C} \Rightarrow \mathbf{x} \in \mathbf{C}$$

- $\mathbf{c}_{\text{init}} \notin \mathbf{C}$
- $\mathbf{c}_{\text{final}} \in \mathbf{C}$

[J. Leroux: TURING'100].



## Theorem

A set  $\mathbf{C} \subseteq \mathbb{N}^d$  is definable in the Presburger arithmetic iff it is a finite union of linear sets:

$$\{\mathbf{b} + n_1\mathbf{p}_1 + \dots + n_k\mathbf{p}_k \mid n_1, \dots, n_k \in \mathbb{N}\}$$

[S. Ginsburg and E. H. Spanier: Pacific journal of mathematics'66]

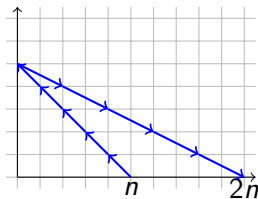
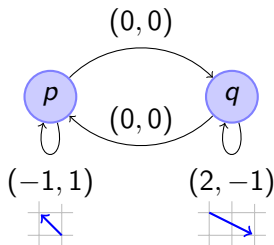


Let  $\mathbf{C}$  be defined as:

$$\mathbf{C} = \left\{ \mathbf{c} \in \mathbb{N}^d \mid \mathbf{c} \xrightarrow{\mathbf{A}^*} \mathbf{c}_{\text{final}} \right\}$$

$\mathbf{C}$  may not be definable in Presburger if  $d > 5$ .

[J. Hopcroft, J.-J. Pansiot:TCS'79]

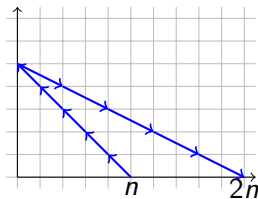
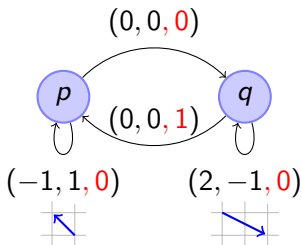


Let  $\mathbf{C}$  be defined as:

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[J. Hopcroft, J.-J. Pansiot:TCS'79]



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A VAS  $\mathbf{A}$  is said to be semilinear from an initial configuration  $\mathbf{c}_{\text{init}}$  if the set of reachable configurations from  $\mathbf{c}_{\text{init}}$  is definable in the Presburger arithmetic.

## Definition (Semilinearity problem)

Deciding if a VAS  $\mathbf{A}$  is semilinear from an initial configuration  $\mathbf{c}_{\text{init}}$ .

Applications:

- Characterize classes for which the most precise inductive invariant is definable in the Presburger arithmetic.
- Characterize the expressive power of acceleration techniques.

## Definition (Semilinearity Witnesses)

A finite sequence of words  $\sigma_1, \dots, \sigma_k \in \mathbf{A}^*$  such that the following set:

$$\mathbf{C} = \left\{ \mathbf{c} \in \mathbb{N}^d \mid \mathbf{c}_{\text{init}} \xrightarrow{\sigma_1^* \dots \sigma_k^*} \mathbf{c} \right\}$$

satisfies for every  $\mathbf{x} \xrightarrow{\mathbf{a}} \mathbf{y}$ :

$$\mathbf{x} \in \mathbf{C} \Rightarrow \mathbf{y} \in \mathbf{C}$$

[J. Leroux:LICS'13]

## Definition (Non Semilinearity Witnesses)

????????????

Applications:

- Detect parts of the reachability set that must be over-approximated for deciding the reachability problem with Presburger inductive invariants.

# Homestate Problem

A set  $\mathbf{C}_{\text{home}}$  of configurations is called a home for a VAS  $\mathbf{A}$  from a set  $\mathbf{C}_{\text{init}}$  of initial configuration if:

$$\forall \mathbf{c} \in \mathbf{C}_{\text{init}} \xrightarrow{\mathbf{A}^*} \mathbf{c} \implies \mathbf{c} \xrightarrow{\mathbf{A}^*} \mathbf{C}_{\text{home}}$$

## Definition (Homestate Problem)

Deciding if a set  $\mathbf{C}_{\text{home}}$  denoted by a Presburger formula  $\phi_{\text{home}}$  is an home set for a VAS  $\mathbf{A}$  from a set of initial configurations  $\mathbf{C}_{\text{init}}$  denoted by a Presburger formula  $\phi_{\text{init}}$ .

Decidable if there exists a finite set  $\mathbf{B} \subseteq \mathbb{N}^d$  and vectors  $\mathbf{p}_1, \dots, \mathbf{p}_k \in \mathbb{N}^d$  such that:

$$\mathbf{C}_{\text{home}} = \bigcup_{\mathbf{b} \in \mathbf{B}} \{ \mathbf{b} + n_1 \mathbf{p}_1 + \dots + n_k \mathbf{p}_k \mid n_1, \dots, n_k \in \mathbb{N} \}$$

## Definition (Non Homestate Witnesses)

- A configuration  $\mathbf{c}$ ,
- A witness of reachability of  $\mathbf{c}$  from  $\mathbf{c}_{init}$ , and
- A witness of unreachability of  $\mathbf{c}$  to  $\mathbf{C}_{home}$ .



## Theorem

Given two VASes  $\mathbf{A}$ ,  $\mathbf{B}$  and two configurations  $\mathbf{c}_{init}$  and  $\mathbf{c}_{final}$  the following property is undecidable:

$$\forall \mathbf{c} \quad \mathbf{c}_{init} \xrightarrow{\mathbf{A}^*} \mathbf{c} \implies \mathbf{c} \xrightarrow{\mathbf{B}^*} \mathbf{c}_{final}$$

[M. Hack:TCS'76]

# Conservative VAS

A VAS  $\mathbf{A}$  is said to be conservative if  $a_1 + \dots + a_d = 0$  for every  $(a_1, \dots, a_d) \in \mathbf{A}$ .

Example:

- Parametrized protocols.

[S. M. German, A. P. Sistla: *journal of ACM*'92].

[B. Aminof, T. Kotek, S. Rubin, F. Spegni, H. Veith: *CONCUR*14].

- Chemical reactions.

## Definition (Homestate Witnesses For Conservative VASes)

A formula  $\phi$  in the Presburger arithmetic denoting a set  $\mathbf{C} \subseteq \mathbb{N}^d$ , and a sequence  $\sigma_1, \dots, \sigma_k \in \mathbf{A}^*$  such that:

- $\mathbf{C}_{\text{init}} \subseteq \mathbf{C}$  and for every  $\mathbf{x} \xrightarrow{\mathbf{a}} \mathbf{y}$  we have  $\mathbf{x} \in \mathbf{C} \Rightarrow \mathbf{y} \in \mathbf{C}$ .
- for every  $\mathbf{c} \in \mathbf{C}$  we have:

$$\mathbf{c} \xrightarrow{\sigma_1^* \dots \sigma_k^*} \mathbf{C}_{\text{home}}$$

[J. Esparza, P. Ganty, J. Leroux, R. Majumdar: CONCUR'15]

Applications:

- Verification problems for parametrized protocols.
- Well specification problem for population protocols.

[D. Angluin, J. Aspnes, Z. Diamadi, M. J. Fischer, R. Peralta:PODC'04]

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# Upward And Downward Closures

## Definition

Let  $(S, \leq)$  be a quasi ordered set.

$$\uparrow x = \{s \in S \mid x \leq s\}$$

$$\uparrow X = \bigcup_{x \in X} \uparrow x$$

$X$  upward closed if  $\uparrow X = X$

$$\downarrow x = \{s \in S \mid s \leq x\}$$

$$\downarrow X = \bigcup_{x \in X} \downarrow x$$

$X$  downward closed if  $\downarrow X = X$

# Ordering Configurations

Let  $\mathbb{N}^d$  be ordered with  $\leq$  defined by:

$$(x_1, \dots, x_d) \leq (y_1, \dots, y_d) \iff \bigwedge_{i=1}^d x_i \leq y_i$$

Upward closed sets are finite unions of  $\uparrow \mathbf{x}$ .

## Example

$$\uparrow(1, 0, 9) = (1, 0, 9) + \mathbb{N} \times \mathbb{N} \times \mathbb{N}$$

Downward closed sets are finite unions of  $X_1 \times \dots \times X_d$  where  $X_i$  is either  $\mathbb{N}$  or a set of the form  $\{0, \dots, n\}$  for some  $n \in \mathbb{N}$ .

## Example

$$\downarrow(1, \omega, 2) = \{0, 1\} \times \mathbb{N} \times \{0, 1, 2\}$$

# Well Quasi Orders (WQO)

## Definition

A quasi ordered set  $(S, \leq)$  is said to be well if it satisfies one of the following properties.

## Lemma

*The following properties are equivalent:*

- *Sets of incomparable elements and decreasing sequences are finite.*
- *Infinite sequences contain a non decreasing pair.*
- *Infinite sequences contain an infinite non decreasing subsequence.*
- *Non decreasing sequences of upward closed sets are stationnary.*
- *Non increasing sequences of downward closed sets are stationnary.*
- *Upward closed sets are upward closures of finite sets.*

# Ideals

Let  $(S, \leq)$  be a well quasi ordered set.

## Definition

An ideal  $I$  is a non-empty downward closed set such that for every  $x, y \in I$ , there exists  $s \in I$  such that  $x, y \leq s$ .

## Theorem

*Every downward closed set is the union of a unique finite family of incomparable ideals.*

[M. Kabil, M. Pouzet : Theor. Inform. Appl'92]

[A. Finkel, J. Goubault-Larrecq : STACS'09]

[J.Goubault-Larrecq, P.Karandikar, K.NarayanKumar, Ph. Schnoebelen : In preparation, 2015].

## Example

$$\text{Ideals}(\mathbb{N}^d, \leq) = \{\downarrow \mathbf{x} \mid \mathbf{x} \in \mathbb{N}_\omega^d\} \quad \text{with} \quad \mathbb{N}_\omega = \mathbb{N} \cup \{\omega\}$$



# Dickson's Lemma

The cartesian product  $(S_1, \leq_1) \times (S_2, \leq_2)$  of two quasi ordered sets is the quasi ordered set  $(S, \leq)$  defined by:

$$(x_1, x_2) \leq (y_1, y_2) \iff x_1 \leq_1 y_1 \wedge x_2 \leq_2 y_2$$

## Lemma (Dickson's Lemma)

*The cartesian product of two well quasi ordered sets is well.*

*Moreover, in that case:*

$$\text{Ideals}(S_1, \leq_1) \times (S_2, \leq_2) = \{I_1 \times I_2 \mid (I_1, I_2) \in \text{Ideals}(S_1, \leq_1) \times \text{Ideals}(S_2, \leq_2)\}$$

# Higman's Lemma

The star  $(S, \leq)^*$  of a quasi ordered set  $(S, \leq)$  is the quasi ordered set  $(S^*, \leq_*)$  where  $S^*$  is the set of words over  $S$ , and  $\leq_*$  is defined by  $w \leq_* w'$  iff

$$w' \in S^* \uparrow_{s_1} S^* \dots \uparrow_{s_k} S^*$$

where  $s_1, \dots, s_k \in S$  satisfy  $w = s_1 \dots s_k$ .

## Lemma (Higman's Lemma)

*The star of a well quasi ordered set is well.*

*Moreover, in that case, ideals of  $(S, \leq)^*$  are finite concatenations  $A_1 \dots A_k$  where  $A_j$  is a language of the form:*

- $\{\varepsilon\} \cup I$  where  $I \in \text{Ideals}(S, \leq)$ , or
- $D^*$  where  $D$  is a finite union of ideals of  $(S, \leq)$ .

[P. Jullien:PhD'69]

[P. A. Abdulla, A. Collomb-Annichini, A. Bouajjani, B. Jonsson:FMSD'04]

[M. Kabil, M. Pouzet : Theor. Inform. Appl'92]

[A. Finkel, J. Goubault-Larrecq : STACS'09]

## Example

Let  $(A, =)$  where  $A$  is a finite alphabet.

$\text{Ideals}(A, =) = \{\{a\} \mid a \in A\}$ .

Ideals of  $(A, =)^*$  have the following form:

$$D_0^* \{\varepsilon, a_1\} D_1^* \dots \{\varepsilon, a_k\} D_k^*$$

where  $D_0, \dots, D_k \subseteq A$  and  $a_1, \dots, a_k \in A$ .

Application :

- Analysis of lossy channel systems [LRE].

[P. A. Abdulla, A. Collomb-Annichini, A. Bouajjani, B. Jonsson:FMSD'04]

# Preruns

Let  $\mathbf{A} \subseteq \mathbb{Z}^d$  be a VAS.

## Definition (Preruns)

A prerun is a triple:

$$(\mathbf{x}, (\mathbf{x}_1, \mathbf{a}_1, \mathbf{y}_1) \dots (\mathbf{x}_k, \mathbf{a}_k, \mathbf{y}_k), \mathbf{y}) \in \mathbb{N}^d \times (\mathbb{N}^d \times \mathbf{A} \times \mathbb{N}^d)^* \times \mathbb{N}^d$$

We introduce  $(\text{preruns}(\mathbf{A}), \trianglelefteq)$  defined as:

$$(\mathbb{N}^d, \leq) \times ((\mathbb{N}^d, \leq) \times (\mathbf{A}, =) \times (\mathbb{N}^d, \leq))^* \times (\mathbb{N}^d, \leq)$$

## Lemma

$(\text{preruns}(\mathbf{A}), \trianglelefteq)$  is well.

[P. Jančar:TCS90]

# Ideals Of Preruns

Ideals of  $(\text{preruns}(\mathbf{A}), \sqsubseteq)$  have the form:

$$(\downarrow \mathbf{x}) \times \left( \bigcup_{t \in T_0} \downarrow t \right) (\{\varepsilon\} \cup \downarrow t_1) \left( \bigcup_{t \in T_1} \downarrow t \right) \dots (\{\varepsilon\} \cup \downarrow t_k) \left( \bigcup_{t \in T_k} \downarrow t \right) \times (\downarrow \mathbf{y})$$

where:

- $\mathbf{x}, \mathbf{y} \in \mathbb{N}_\omega^d$ .
- $t_1, \dots, t_k \in \mathbb{N}_\omega^d \times \mathbf{A} \times \mathbb{N}_\omega^d$ .
- $T_0, \dots, T_k$  are finite subsets of  $\mathbb{N}_\omega^d \times \mathbf{A} \times \mathbb{N}_\omega^d$ .

Notice that:

$$\downarrow(\mathbf{u}, \mathbf{a}, \mathbf{v}) = \downarrow \mathbf{u} \times \{\mathbf{a}\} \times \downarrow \mathbf{v}$$

## Definition

A run is a prerun

$$(\mathbf{x}, (\mathbf{x}_1, \mathbf{a}_1, \mathbf{y}_1) \dots (\mathbf{x}_k, \mathbf{a}_k, \mathbf{y}_k), \mathbf{y})$$

satisfying for every  $1 \leq j \leq k$ :

- $\mathbf{y}_{j-1} = \mathbf{x}_j \wedge \mathbf{y}_j = \mathbf{x}_{j+1}$  with the convention  $\mathbf{y}_0 = \mathbf{x}$  and  $\mathbf{x}_{k+1} = \mathbf{y}$ .
- $\mathbf{x}_j \xrightarrow{\mathbf{a}_j} \mathbf{y}_j$ .

We let  $\text{runs}(\mathbf{x}, \mathbf{A}, \mathbf{y})$  be the set of runs from  $\mathbf{x}$  to  $\mathbf{y}$ .

# A CEGAR Approach

The reachability problem reduces to the emptiness of  $\downarrow\text{runs}(\mathbf{x}, \mathbf{A}, \mathbf{y})$ .

$D := \text{preruns}(\mathbf{A})$

While there exists a maximal ideal  $I$  of  $D$  with  $I \not\subseteq \downarrow\text{runs}(\mathbf{x}, \mathbf{A}, \mathbf{y})$

    Pick  $\pi \in I \setminus \downarrow\text{runs}(\mathbf{x}, \mathbf{A}, \mathbf{y})$

$D := D \setminus \uparrow\pi$

return  $D$

[J. Leroux, S. Schmitz:LICS'15]

# The Kosaraju Approach

## Theorem

*The Kosaraju algorithm is computing precisely the decomposition of  $\downarrow \text{runs}(\mathbf{x}, \mathbf{A}, \mathbf{y})$  into ideals.*

[J. Leroux, S. Schmitz:LICS'15]

## Applications:

- Demystifying the Kosaraju algorithm for deciding the reachability problem.
- Provide a guideline for deciding reachability problems for VAS extensions.



Ideals of the decomposition of  $\downarrow\text{runs}(\mathbf{x}, \mathbf{A}, \mathbf{y})$  have the form:

$$(\downarrow\mathbf{x}) \times \left( \bigcup_{t \in T_0} \downarrow t \right) (\{\varepsilon\} \cup \downarrow t_1) \left( \bigcup_{t \in T_1} \downarrow t \right) \dots (\{\varepsilon\} \cup \downarrow t_k) \left( \bigcup_{t \in T_k} \downarrow t \right) \times (\downarrow\mathbf{y})$$

where  $T_j \subseteq \mathbb{N}_\omega^d \times \mathbf{A} \times \mathbb{N}_\omega^d$  denotes the transitions of a strongly connected graph.

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# About Witnesses

Many problems on VASes can be decided with simple witnesses.  
There exist decidable (EXPSPACE) logics for expressing some of these witnesses:

[H.-C. Yen: Inf. Comput.'92]

[M. F. Atig, P. Habermehl: Int. J. Found. Comput. Sci'11]

[M. Blockelet, S. Schmitz: MFCS'11]

[S. Demri: INFINITY'11]

[J. Leroux, M. Praveen, G. Sutre: CONCUR'13]

The following problems can be decided this way:

- Boundedness/place boundedness/selective unboundedness.
- Regularity/context-freeness. [J. Leroux, V. Penelle, G. Sutre: LICS'13]
- Coverability.
- Termination.

# About Ideals

Well-structured transition systems is a powerful framework for solving coverability questions [A. Finkel, Ph. Schnoebelen: TCS'01]. Concerning reachability ones, we have a new ideal tool.

Possible applications of ideals of runs:

- VAS with 1 zero test.
- VAS with resets.
- Pushdown VAS.
- Branching VAS.
- Data nets.