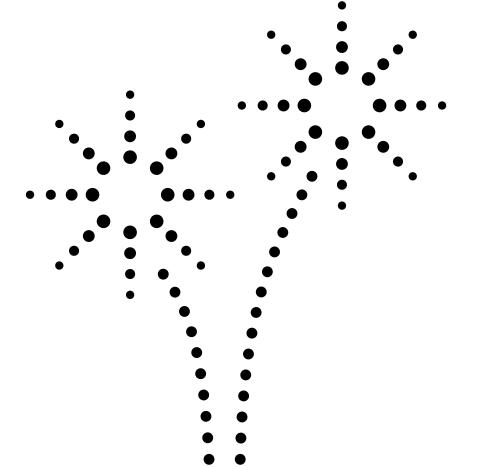
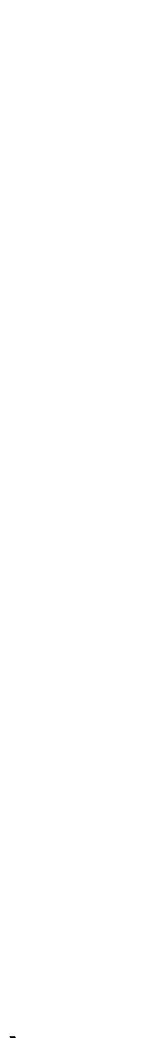
On the Home-Space Problem for Petri Nets

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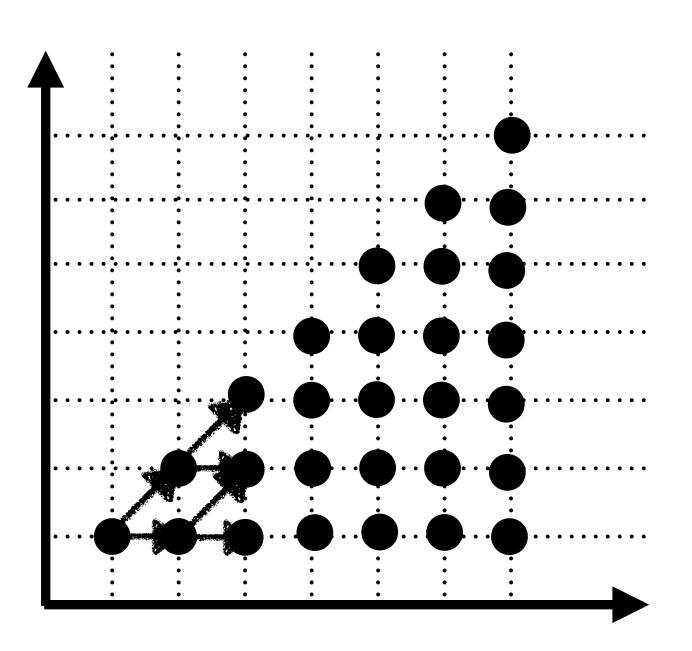


Semilinear Sets



Linear Sets

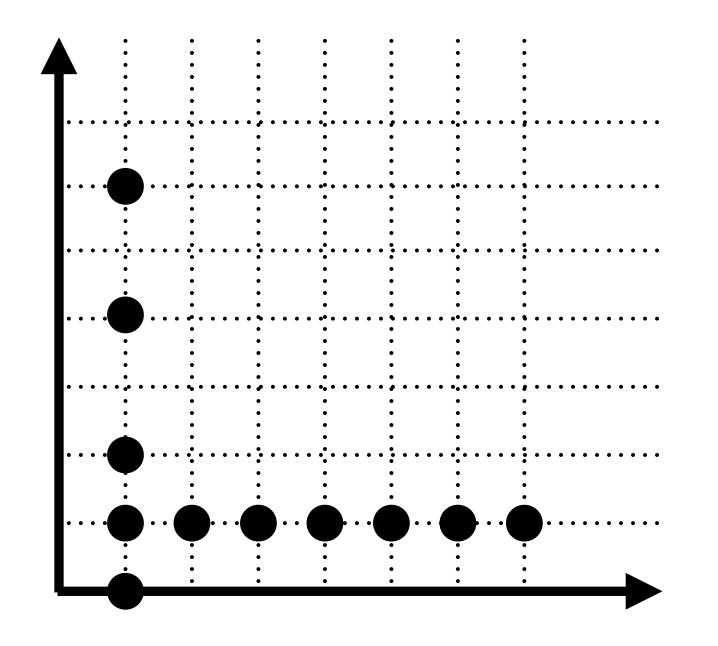
A linear set of \mathbb{N}^d is a set of the form $b + \mathbb{N}p_1 + \cdots + \mathbb{N}p_k$ where $b, p_1, \ldots, p_k \in \mathbb{N}^d$.



$(1,1) + \mathbb{N}(1,1) + \mathbb{N}(1,0)$

Sereir Sets

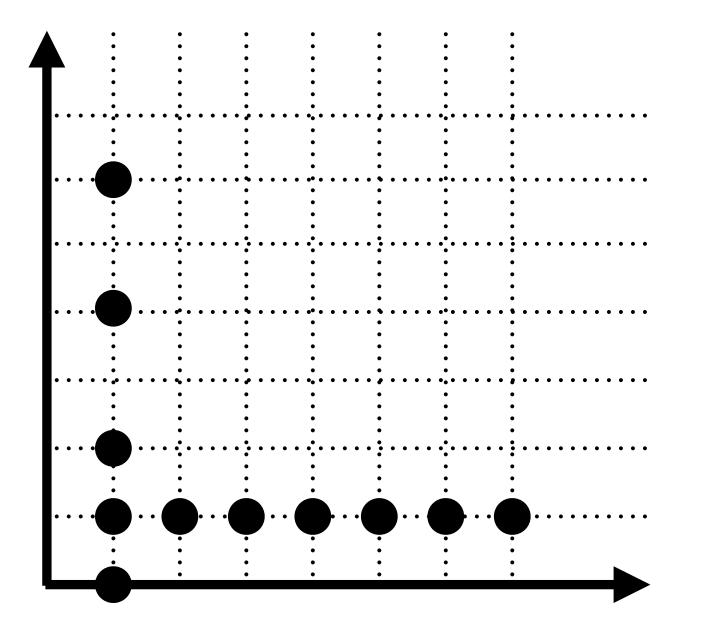
A semilinear set is a finite union of linear sets.



 $(1,1) + \mathbb{N}(1,0) \cup (1,0) + \mathbb{N}(0,2)$

Presburger Arithmetic

1966, Ginsburg and Spanier : Sets definable in the Presburger arithmetic $FO(\mathbb{N}, +, 0, 1, \leq , (\equiv_k)_{k \in \mathbb{N}})$ are precisely the semilinear sets.



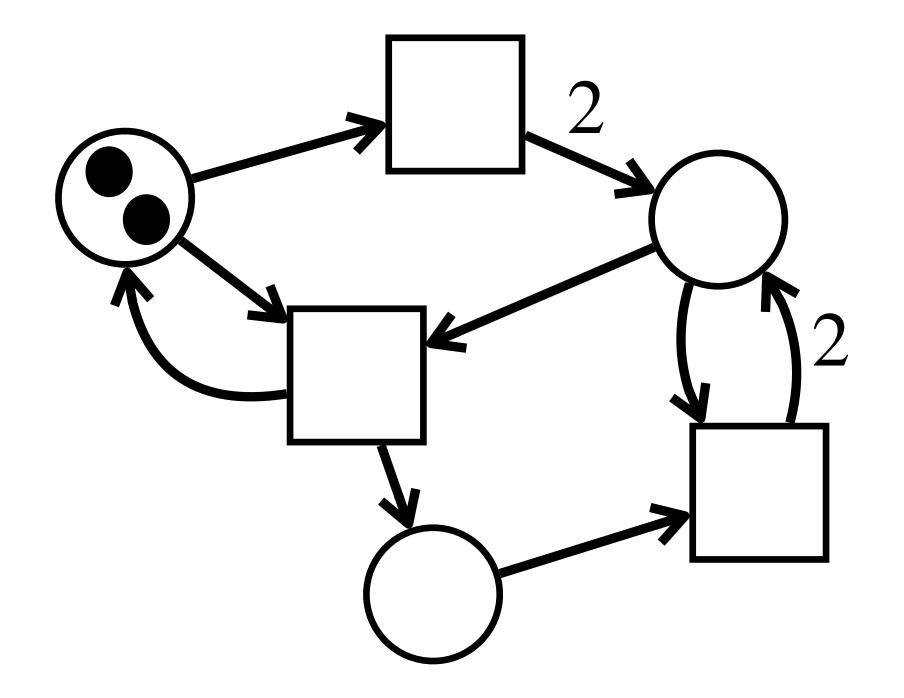
 $\{(x, y) \in$

$$(1,1) + \mathbb{N}(1,0) \cup (1,0) + \mathbb{N}(0,2) =$$
$$\mathbb{N}^2 \mid (x \ge 1 \land y = 1) \lor (x = 1 \land y \equiv_2 0) \}$$

Petri Nets



Petri Nets



Petri Nets

Model of concurrency with extensive applications:

- hardware and software,
- database systems,
- chemical, biological and business processes.

Reachability Problem

INPUT:

- A Petri net and two configurations *x*, *y*. OUTPUT:
- Decide whether $x \rightarrow y$.

Central Problem

Many problems reduce to the Petri net reachability problem:

- Formal languages.
- Logic.
- Concurrent systems.
- Process calculi.
- Population protocols.

Short History

- 1976, Lipton : Expspace lower-bound.
- 1981, Mayr : Decidable.
- 1982, Kosaraju and in 1992 Lambert clarified the algorithm.
- 2015, L. and Schmitz : Cubic-Ackermann upper-bound.
- 2019, L. and Schmitz : Ackermann upper-bound.
- 2019, Czerwinski, Lasota, Lazic, L., and Mazowiecki : Tower lower-bound.
- 2021, L., and Czerwinski and Orlikowski : Ackermann lower-bound.

 \Rightarrow The Petri net reachability problem is Ackermann-complete.

Semilinear Reachability Problem

INPUT:

- A Petri net and two semilinear sets X, Y of configurations. OUTPUT:
- Decide whether $X \xrightarrow{*} Y$.

i.e. $\exists x \in X \ \exists y \in Y \ x \xrightarrow{*} y$

Home-Space



Home-Space

Given a Petri net and two sets of configurations X, H. H is called an home-space for X if:



 $\forall y \quad X \xrightarrow{*} y \quad \Rightarrow \quad y \xrightarrow{*} H$

Semilinear Home-Space Problem

INPUT:

- A Petri net and two semilinear sets of configurations X, H. OUTPUT:
- Decide whether *H* is an home-space for *X*.

Semilinear Non-Reachability Problem \sim **Semilinear Home-Space Problem**

- H home-space for X iff $post^*(X) \subseteq pre^*(H)$

 $\neg(X \xrightarrow{*} Y)$ iff post*(X) \subseteq pre*(Y)

History

- 1973, Henry G. Baker Jr : $post_A^*(x) \subseteq pre_B^*(y)$ undecidable if $A \neq B$
- decidable for hybrid linear sets H.

Our main contributions :

- The semilinear home-space problem is decidable.
- Moreover it is Ackermann-complete.

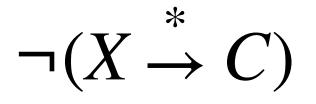
1989, Davide de Frutos Escrig and Colette Johnen : Home-space problem is

Inductive Non-Reachability Cores

C is called an inductive non-reachability core for H if:

- $post^*(C) = C$
- $C \cap H = \emptyset$
- $\forall x \quad x \xrightarrow{*} (H \cup C)$

In that case *H* is an home-space for *X* iff $\neg(X \rightarrow C)$



Stability Property

Theorem

If C_i is an inductive non-reachability core for H_i for every $1 \le i \le n$ then $C_1 \cap \ldots \cap C_n$ is an inductive non-reachability core for $H_1 \cup \ldots \cup H_n$.

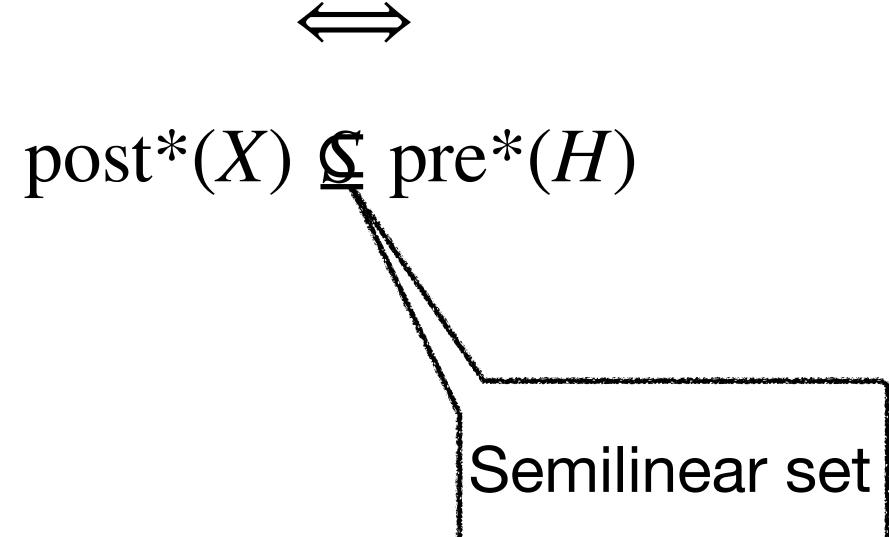
1st Result

computable.

• Semilinear inductive non-reachability cores for semilinear sets are effectively

2nd Result

A semilinear set H is an home-space for a semilinear set X

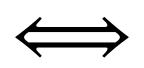


Refined 2nd Result

there exists a semilinear inductive invariant I and words w_1, \ldots, w_k such that:

 $X \subseteq I \subseteq \operatorname{pre}(H, w_1^* \dots w_k^*)$

A semilinear set H is an home-space for a semilinear set X



Future Work & Open Problems

Variants

does there exist a configuration h such that $\{h\}$ is an home-space.

Open variant :

Given a Petri net and a semilinear set X of initial configurations, does there exists a semilinear set $H \subseteq \text{post}^*(X)$ that is an home-space for X.

2016, Eike Best and Javier Esparza : The existential variant is decidable i.e. :

Inductive Non-reachability Core Problem

INPUT:

- A Petri net and two semilinear sets C, H of configurations. OUTPUT:
- Decide whether C is an inductive non-reachability core for H.

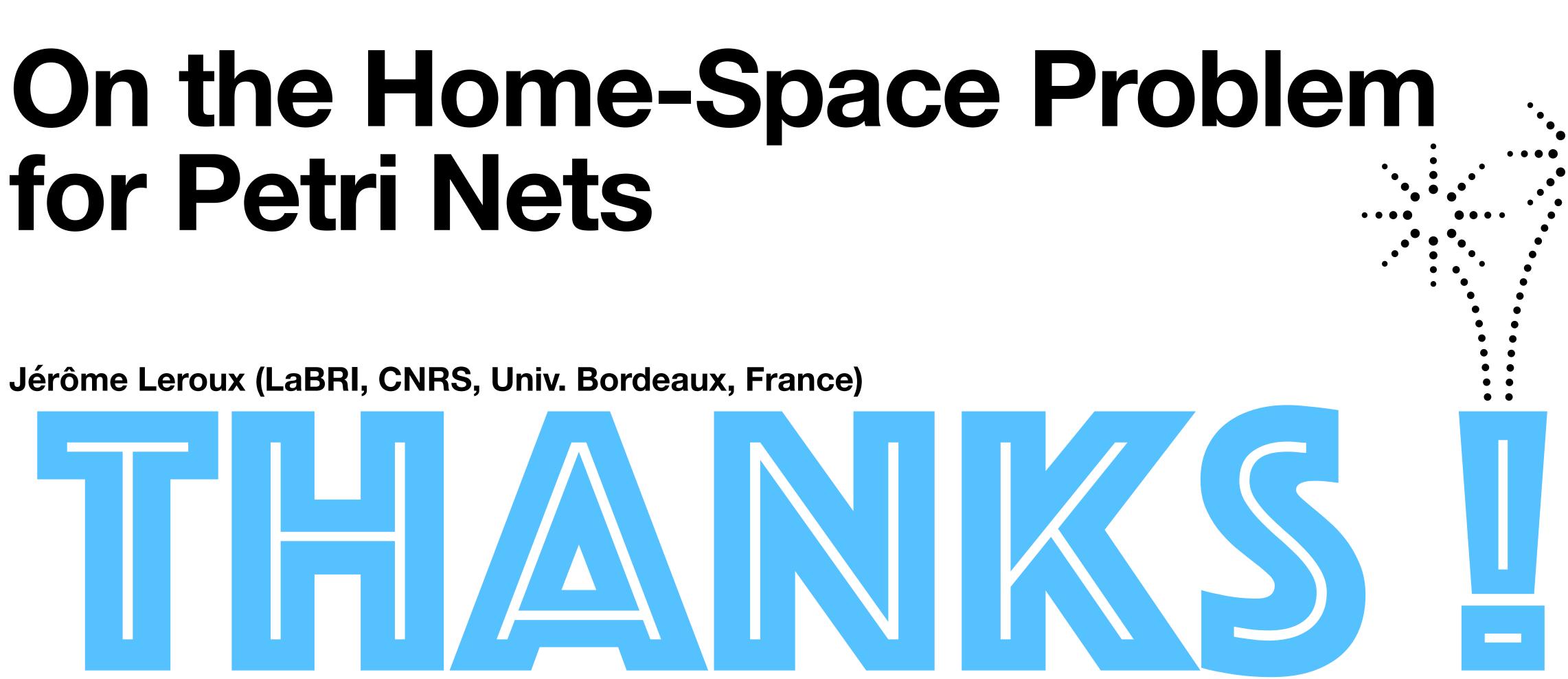
Universal Reachability Problem

INPUT:

- A Petri net and a semilinear set X of configurations. OUTPUT:
- Decide whether $post^*(X)$ is the full set of configurations.

2018, Petr Jančar, L., Grégoire Sutre: Expspace-complete for singleton X and decidable in general.

for Petri Nets



Joint work with Petr Jančar (Dept of Comp. Sci., Faculty of Science, Palacky Univ. Olomouc, Czechia)