Rewriting Models of Boolean Programs

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Joint work with Ahmed Bouajjani

Initiated in the early 80s in USA and France.

• 25 Years of Model Checking Workshop on August 16

Exhaustive examination of the state space using (hopefully) clever techniques to avoid state explosion.

Very successful for hardware or "low-level" software:

- Applied to commercial microprocessors, telephone switches launching protocols, brake systems, or the dutch Delta works.
- Model-checking groups at all major hardware companies.
- ACM Software System Award 2001, Gödel Prize 2000, Kannellakis Awards 1998 and 2005.

Big research challenge of the 00s: extension to 'high-level' software.

Three main research questions:

- Integration of the tools in the software development process.
 - Users trust their hardware but may not trust their software: "post-mortem" verification, "backstage" verification tools ...
- Automatic extraction of models from code.
- Algorithms for infinite-state systems.
 - Software systems "more often" infinite-state.

The lazy approach to software verification

Construct a sequence of increasingly faithful models that under- or overapproximate the code.

Underapproximations: 32-bit integer \rightarrow 2-bit integer, 500MB heap \rightarrow 10B heap.

Overapproximations using predicate abstraction:

- Define a set of predicates over the dataspace (e.g. x < y, "list is empty").
- Partition the dataspace into 2^{number of predicates} abstract values.
- Execute symbolically: one boolean variable per predicate.

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Both are boolean programs:

- Same control-flow structure as code + possibly nondeterminism.
- Only one datatype: booleans.
- Conceptually could also take any enumerated type but booleans are the bridge to SAT and BDD technology.

Boolean programs are still pretty complicated objects:

- Procedures/methods and recursion.
- Concurrency and communication (threads, cobegin-coend sections).
- Object-orientation.

Must be "compiled" into simpler and formal models.

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Use rewriting to model boolean programs. In a nutshell:

- Model program states as terms.
- Model program instructions as term-rewriting rules.
- Model program executions as sequences of rewriting steps.

Reachability

- But reachability between two states not enough for verification purposes.
- Safety properties often characterized by an infinite set of dangerous states.

Symbolic reachability: Find a finite symbolic representation of the (possibly infinite) set of states reachable or backward reachable from a given (possibly infinite) set of states.

- pre*(S) denotes the set of predecessors of S.
 (states backward reachable from states in S)
- post*(S) denotes the set of successors of S.
 (states forward reachable from states in S)

Rewriting models for:

- Procedural sequential programs.
- Multithreaded while-programs.
- Multithreaded procedural programs.
- Procedural programs with cobegin-coend sections.

For each of those:

- Complexity of the reachability problem.
- Finite representations for symbolic reachability.

A rewriting model of procedural sequential programs

State of a procedural boolean program: $(g, \ell, n, (\ell_1, n_1) \dots (\ell_k, n_k))$, where

- g is a valuation of the global variables,
- ℓ is a valuation of local variables of the currently active procedure,
- *n* is the current value of the program pointer,
- l_i is a saved valuation of the local variables of the caller procedures, and
- n_i is a return address.

Modelled as a string $g \langle \ell, n \rangle \langle \ell_1, n_1 \rangle \ldots \langle \ell_k, n_k \rangle$

Instructions modelled as string-rewriting rules, e.g. $t \langle t, m_0 \rangle \rightarrow f \langle f t f, p_0 \rangle \langle t, m_1 \rangle$ Prefix-rewriting policy:

$$\frac{U \to W}{U \lor \frac{r}{\longrightarrow} W \lor V}$$

An example

bool function $foo(\ell)$

- f_0 : if ℓ then
- *f*₁: return false else
- *f*₂: **return** true **fi**

procedure main()global b m_0 : while b do m_1 : b := foo(b) od; m_2 : return

- $\begin{array}{rcl} b \langle t, f_0 \rangle & \to & b \langle t, f_1 \rangle \\ b \langle f, f_0 \rangle & \to & b \langle f, f_2 \rangle \\ b \langle \ell, f_1 \rangle & \to & f \\ b \langle \ell, f_2 \rangle & \to & t \end{array}$
 - $t m_0 \rightarrow t m_1$ $f m_0 \rightarrow f m_2$ $b m_1 \rightarrow b \langle b, f_0 \rangle m_0$ $b m_2 \rightarrow \epsilon$

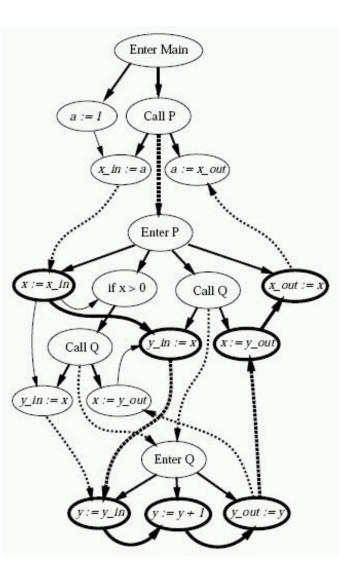
(b and ℓ stand for both t and f)

Comparison with Horwitz, Reps, and Binkley 90

procedure Q(y) $q_0: y := y + 1$ $q_1:$ return

procedure P(x) p_0 : if x > 0 then p_1 : call Q(x)fi; p_2 : call Q(x) p_3 : return

```
procedure Main();
local a
m_0: a := 1
m_1: call P(a)
m_2: return
```



$$egin{array}{rcl} \langle y, q_0
angle & o & \langle y+1, q_1
angle \ \langle y, q_1
angle & o & \epsilon \end{array}$$

$$egin{array}{rcl} \langle a,m_0
angle &
ightarrow & \langle 1,m_1
angle \ \langle a,m_1
angle &
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angle\langle a,m_2
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Theorem: Given an effectively regular (possibly infinite) set S of strings, the sets $pre^*(S)$ and $post^*(S)$ are also effectively regular.

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Polynomial algorithms by Bouajjani, E., Maler and Finkel, Willems, Wolper in 97.

Saturation algorithms: the automata for pre*(S) and post*(S) are essentially obtained by adding transitions to the automaton for S.
 (Algorithms for similar models by Alur, Etessami, Yannakakis, and Benedikt, Godefroid, Reps and ...)

BDD-based algorithms by E. and Schwoon in 01.

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"Model Checking an Entire Linux Distribution for Security Violations" by Schwarz et al. at ACSAC 05.

Büchi did it



Moshe Vardi, 25MC Workshop:

Büchi automata, introduced by Büchi in the early 60s to solve problems in second-order number theory, have been translated, unlikely as it may seem, into effective algorithms for model checking tools.

Büchi did it twice



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This talk:

Regular canonical systems, introduced by Büchi in the early 60s because he liked them, have been translated, unlikely as it may seem, into effective algorithms for software model checking tools.

A rewriting model of multithreaded while-programs

Communication through global variables.

State determined by: $\{g, (\ell_0, n_0), (\ell_1, n_1) \dots (\ell_k, n_k)\}$ where

- g is a valuation of the global variables,
- ℓ_i is a valuation of the local variables of the *i*-th thread, and
- n_i is the value of the program pointer of the *i*-th thread.

Modelled as a multiset

 $g \parallel \langle \ell_0, n_0 \rangle \parallel \langle \ell_1, n_1 \rangle \parallel \ldots \parallel \langle \ell_k, n_k \rangle$

Instructions modelled as multiset-rewriting rules, e.g.

 $tf \parallel m_0 \to ff \parallel m_1 \parallel \langle f, p_0 \rangle$

Multiset rewriting, or rewriting modulo assoc. and comm. of \parallel .

An example

thread p() p_0 : if ? then p_1 : b := trueelse p_2 : b := falsefi; p_3 : end

 $b \parallel p_0 \rightarrow b \parallel p_1$ $b \parallel p_0 \rightarrow b \parallel p_2$ $b \parallel p_1 \rightarrow t \parallel p_3$ $b \parallel p_2 \rightarrow f \parallel p_3$ $b \parallel p_3 \rightarrow \epsilon$

thread main()
global b

 m_0 : while *b* do m_1 : fork p()od;

 m_2 : end

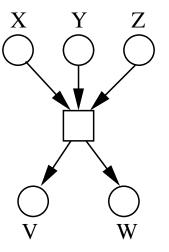
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Multiset rewriting

Theorem [Mayr, Kosaraju, Lipton, 80s]: The reachability problem for multiset-rewriting is decidable but EXPSPACE-hard.

- Equivalent to the reachability problem for Petri nets.
- A place for each alphabet letter.
- A Petri net transition for each rewrite rule.

$$X \parallel Y \parallel Z \longrightarrow V \parallel W$$



Algorithms (not only proofs) quite complicated.

Negative results for $pre^*(\{s\})$ and $post^*(\{s\})$.

Upward-closed set: if some multiset *t* belongs to the set, then $t \parallel t'$ also belongs to the set for every t'.

Finitely representable e.g. by the its of minimal elements.

Upward-closed sets capture properties that can be decided by inspecting a bounded number of threads (e.g. mutual exclusion).

Theorem [Abdulla et al. 96]: Given a multiset-rewriting system and an upward-closed set of states S, the set $pre^*(S)$ is upward-closed and effectively constructible.

• Very simple algorithm: compute *pre*(S), *pre*²(S), *pre*³(S)....

Extensions applied to multithreaded Java [Delzanno, Raskin, Van Begin 04].

Monadic rules \equiv no global variables \equiv no communication

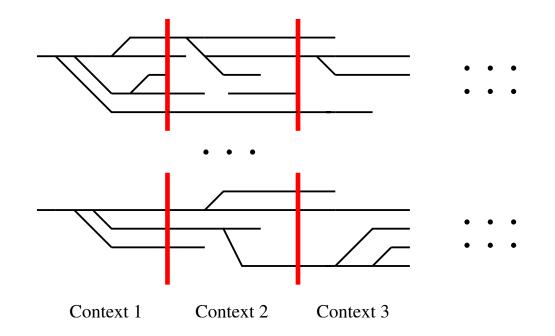
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... but what are threads that cannot communicate with each other good for?!!!

Monadic multiset-rewriting

Monadic rules \equiv no global variables \equiv no communication

... but what are threads that cannot communicate with each other good for?!!! They are good for underapproximations [Qadeer and Rehof 05]



Theorem [Huyhn 85, E.95]: The reachability problem for monadic multiset-rewrite systems is NP-complete.

- Membership in NP not completely trivial.
- Hardness very easy, reduction from SAT:

A thread for each variable x_i that (a) nondeterministically chooses $I_i \in \{x_i, \overline{x}_i\}$ and (b) spawns a clause thread for each clause satisfied by I_i .

The thread for a clause does nothing and terminates.

Formula satisfiable iff there is state at which one thread per clause is active.

Semi-linear sets usually defined as subsets of \mathbb{N}^n .

- Finite union of linear sets.
- { $r + \lambda_1 p_1 + \ldots + \lambda_n p_n \mid \lambda_1, \ldots, \lambda_n \in \mathbb{N}$ }.

Language interpretation: "commutative closure" of the regular languages.

Similar properties to regular languages: closure under boolean operations, decidable (but no longer polynomial) membership problem, etc.

Theorem [E.95]: Given a monadic multiset-rewriting system and a semi-linear set of states S, the sets $post^*(S)$ and $pre^*(S)$ are semi-linear and effectively constructible.

Multithreaded procedural programs

Two-counter machines can be simulated by a program with two recursive threads communicating over two global (boolean) variables:

- Tops of the recursion stacks contains two copies of the machine's control point.
- Depths the two recursion stacks model the values of the counters.
- Calls and returns model increasing and decrementing the counters.
- One variable to ensure alternation of moves.
- One variable to keep the two copies of the control point "synchronized".

If communication takes place by rendezvous the two variables are no longer needed: programs without variables are still Turing powerful.

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Communication-free case: [Bouajjani, Müller-Olm and Touili 05]

Communication through nested locks: [Kahlon and Gupta 06]

A rewriting model for the communication-free case

State of a multithreaded procedural program without global variables: multiset $\{s_1, s_2, ..., s_k\}$ of states of procedural programs, where

 $s_i = (\ell_{i0}, n_{i0}) (\ell_{i1}, n_{i1}) \dots (\ell_{im}, n_{im})$

Modelled as a string $\# w_k \# w_{k-1} \# \dots \# w_1$ where $w_i = \langle \ell_{i0}, n_{i0} \rangle \langle \ell_{i1}, n_{i1} \rangle \dots \langle \ell_{im}, n_{im} \rangle$

Instructions modelled as string-rewriting rules. A new thread is inserted to the left of its creator, e.g.

 $\# \langle b, m_1 \rangle \longrightarrow \# p_0 \# \langle f, m_3 \rangle$

Threads "in the middle" of the string should also be able to "move": back to ordinary rewriting

 $\frac{u \longrightarrow w}{v_1 \ u \ v_2 \longrightarrow v_1 \ w \ v_2}$

An example

process $p()$;	
<i>p</i> ₀ :	if (?) then
<i>p</i> ₁ :	call $p()$
	else
<i>p</i> ₂ :	skip
	fi;
<i>p</i> 3:	return
proc	ess main()
proce m ₀ :	ess <i>main</i> () if (?) then
-	
<i>m</i> ₀ :	if (?) then
<i>m</i> ₀ :	if (?) then fork <i>p</i> ()
m ₀ : m ₁ :	if (?) then fork <i>p</i> () else

- $\begin{array}{rccc} \# p_0 & \rightarrow & \# p_1 \\ \# p_0 & \rightarrow & \# p_2 \\ \# p_1 & \rightarrow & \# p_0 p_3 \\ \# p_2 & \rightarrow & \# p_3 \\ \# p_3 & \rightarrow & \# \end{array}$

Theorem [BMOT05]: For every effectively regular set S of states, the set $pre^*(S)$ is regular and a finite-state automaton recognizing it can be effectively constructed in polynomial time.

• Similar to *pre** for monadic string-rewriting [Book and Otto 93].

Theorem [BMOT05]: For every effectively context-free set S of states, the set $post^*(S)$ is context-free and a pushdown automaton recognizing it can be effectively constructed in polynomial time.

Counterexample to regularity: *P* that spawns a copy of *Q* and calls itself.

The number of threads is equal to the depth of the recursion.

Reachability set: $\{(\#q)^n \#p^{(n+1)} | n \ge 0\}.$

Difference with threads: implicit synchronization induced by the coend.

- "Threads have to wait for its siblings to terminate."
- Corresponds to calling procedures in parallel.

Rewriting model only works well for the communication-free (monadic) case.

States modelled as terms with both \parallel and \cdot as infix operators e.g.

 $(\langle t, p_1 \rangle \parallel q_2) \cdot \langle t f, m_1 \rangle$

Rewriting modulo assoc. of \cdot and assoc. and comm. of \parallel .

This model is called monadic process rewrite systems (monadic PRS) [Mayr 00].

Symbolic reachability with commutative hedge automata (CHA) [Lugiez 03].

Theorem [Bouajjani and Touili 05]: Given a monadic PRS, for every CHA-definable set of terms T, the sets $post^*(T)$ and $pre^*(T)$ are CHA-definable and effectively constructible.

Weaker approach: construct not the sets $post^*(T)$ or $pre^*(T)$ themselves, but representatives w.r.t. the equational theory.

Sufficient for control reachability problems.

Theorem [Lugiez and Schnoebelen 98, E. and Podelski 00]:

Let *R* be a monadic PRS and let *A* be a bottom-up tree automaton. One can construct in $O(|R| \cdot |A|)$ time bottom-up tree automata recognizing a set of representatives of *post*^{*}(*L*(*A*)) and *pre*^{*}(*L*(*A*)). Rewriting concepts can be used to give elegant semantics to programming languages.

- String/multiset rewriting correspond to sequential/parallel computation.
- Monadic/non-monadic rewriting correspond to absence or presence of communication.
- Rewriting modulo useful for combining concurrency and procedures.

Symbolic reachability is the key problem to solve.

Comparison with process algebras:

- Process algebras have a notion of hiding or encapsulation.
- Rewriting much closer to automata theory \rightarrow algorithms.