Beyond Big-Oh analysis in automata theory

Javier Esparza

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- A paper deserves publishing iff it provides new or better bounds.

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- Automata theory for verification very much profits from "beyond Big-Oh" analysis and prototype implementations.

Today's menu

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• Appetizer: Universality of finite automata

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- Main course: Emptiness of Büchi automata

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- Dessert: Universal search

Universality of finite automata

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Complexity:

 $O(2^{|A|})$ time and space, and $\Theta(2^{|A|})$ for some family.

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Subsumption check [DeWDHR06]:

If the powerset construction generates states $Q_1 \subseteq Q_2$, redirect Q_2 's incoming arcs to Q_1 and remove Q_2 .

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- Assume $Q_1 \subseteq Q_2$. We have $L_B(Q_1) \subseteq L_B(Q_2)$ and if *B* universal then $L_B(Q_1) = L_B(Q_2)$.
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- Let B' be the result of the operation. Then $L_{B'} \subseteq L_B$ and if B universal then $L_{B'} = L_B$.

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- Let B' be the result of the operation. Then $L_{B'} \subseteq L_B$ and if B universal then $L_{B'} = L_B$.
- So B' universal iff B universal iff A universal.

Potential application to verification

Typical scenario

- System: communicating automata A_1, A_2, \ldots, A_n .
- Specification (allowed behaviour): automaton B.
- System's behaviour: automaton $A = A_1 \otimes A_2 \otimes \ldots \otimes A_n$.
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- Check emptiness of $A \times \overline{B}$.

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- Compute $A = A_1 \otimes \ldots \otimes A_n$. Possible blowup!
- Check emptiness of $A \times \overline{B}$.

Alternative approach: $L(A) \subseteq L(B)$ iff $\overline{L(A)} \cup L(B) = \Sigma^*$

- Compute $\overline{A} = \overline{A}_1 \oplus \ldots \oplus \overline{A}_n$.
- Check universality of $A + \overline{B}$. Possible blowup!

Emptiness of Büchi automata

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The problem

```
Given: a Büchi automaton A. Decide: is L(A) = \emptyset ?
```

Lassos

A is nonempty iff it contains an accepting lasso: a path leading from some initial state to some accepting state, followed by a cycle.

A trivial quadratic algorithm

The algorithm

- (1) Compute all reachable final states.
- (2) For every final state q:
 - check if q is reachable from itself.
 - if so, stop and answer "nonempty".

Answer "empty".

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- (1) takes O(|A|) time.
- (2) takes O(|A|²) time, and there is a family of graphs for which it takes ⊖(|A|²).

A first linear algorithm: double-DFS [CVWY91]

(1) Use DFS to compute a list $\alpha_1, \alpha_2, \ldots, \alpha_k$ of all reachable accepting states

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(2) For i = 1 to k:
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- (1) Use DFS to compute a list α₁, α₂,..., α_k of all reachable accepting states sorted in postorder.
 (a state is added to list when **backtracking** from it)
- (2) For i = 1 to k:
 - use a modified DFS to check if α_i is reachable from itself without visiting any state reachable from $\alpha_1, \ldots, \alpha_{i-1}$.
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 - not yet discovered by the first phase;
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Space complexity

- For each state we have three possible situations:
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 - discovered by the first, but not yet by the second;
 - discovered by both phases.
- 2 additional bits per (reachable) state.

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Proof:

• Consider the case k = 2 (two final states α_1, α_2).

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- Consider the case k = 2 (two final states α_1, α_2).
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- Call these cycles blocked.

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- If there is a blocked cycle, then $\alpha_1 \rightsquigarrow \alpha_2$.
- If $(\alpha_1 \rightsquigarrow \alpha_2 \land \alpha_2 \rightsquigarrow \alpha_1)$ then some cycle contains α_1 .
- So it suffices to guarantee: if $\alpha_1 \rightsquigarrow \alpha_2$ then $\alpha_2 \rightsquigarrow \alpha_1$.
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- We show that postorder implies this.
- Look at DFS as a recursive procedure dfs(q).
- Let ca(q) denote the time at which dfs(q) is called.
- Let *ret(q)* denote the time at which *dfs(q)* returns.
 (The search backtracks from *q*.)

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 (The search backtracks from *q*.)
- Postorder assumption: $ret(\alpha_1) < ret(\alpha_2)$.

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- By proper nesting of calls we have either:
 - $ca(\alpha_1) < ret(\alpha_1) < ca(\alpha_2) < ret(\alpha_2)$ or
 - $ca(\alpha_2) < ca(\alpha_1) < ret(\alpha_1) < ret(\alpha_2)$

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- Case 1: $ca(\alpha_1) < ret(\alpha_1) < ca(\alpha_2) < ret(\alpha_2)$. Then $\alpha_1 \not \rightarrow \alpha_2$.
- Case 2: $ca(\alpha_2) < ca(\alpha_1) < ret(\alpha_1) < ret(\alpha_2)$. Then $\alpha_2 \rightsquigarrow \alpha_1$.

End of the story? No!

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Counterexample: path to accepting state α_i + cycle.
Double-DFS requires to store paths for all accepting states.

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- Counterexample: just pop the call stack!
- Correctness: Easy. The second searches are exactly as in the double-DFS algorithm.

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A search algorithm for Büchi emptiness is optimal if it terminates immediately after the set of transitions it has explored contains an accepting lasso.

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The nested-DFS algorithm is not optimal!

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[Schwoon, E. 05]

These two improvements still require only 2 additional bits per state: four-colour algorithm.

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Question

Are there optimal (linear-time) algorithms?

Approach

- Identify the reachable (nontrivial) SCCs of A.
- Check if some of them contains an accepting state.

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- Automaton $A \Rightarrow$ dag of SCCs.
- Root of a SCC: the first node of the SCC discovered by the DFS.

(The definition of root refers to a particular, fixed DFS-run!)

 If ρ is a root, then at time ret(ρ) the DFS has discovered all nodes of ρ's SCC and its descendants in the dag.

First idea

- Push all discovered nodes in a new stack (Tarjan's stack).
- For every root ρ: at time ret(ρ), pop from Tarjan's stack until ρ is popped; the popped nodes constitute ρ's SCC.

GOD's contribution: Oracle

For a given state q oracle decides if q is a root.

1 T(q)2 push(q, Stack);3 for each transition $q \rightarrow r$ 4 if *r* not yet explored then T(r)5 if *q* is a root then 6 repeat s := pop(Stack) until s = q

Implementing the oracle

Problem

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Second idea

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Order induced by call purphere is all that matters)

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Second idea

 Annotate each state q with ca(q) and a lowlink-number lowlink(q).

- Iowlink(q): lowest ca(r) of states r satisfying
 - q and r lie in the same SCC, and
 - *r* reachable from *q* through states not yet discovered at time *ca*(*q*).

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- $lowlink(q) \le ca(q)$ for every state q.
- Fact: lowlink(q) = ca(q) if and only if q is a root.

Tarjan's algorithm

Miracle

lowlink(q) can be easily determined at time *ret*(q).

Miracle

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Main observation of [GV04]:

 α belongs to a cycle iff $T(\alpha)$ reaches some state *r* satisfying two conditions:

- $r \in Stack$, and
- $lowlink(r) < ca(\alpha)$.

Add a new parameter to the procedure to keep track of the last visited accepting state.

1	$GV(\boldsymbol{q}, \alpha)$
2	push(<i>q</i> , <i>Stack</i>);
3	for each transition $q \rightarrow r$
4	if <i>r</i> not yet explored then
5	if r accepting then $GV(r, r)$ else $GV(r, \alpha)$;
6	<i>r.lowlink</i> := min(<i>q.lowlink</i> , <i>r.lowlink</i>)
7	else if $r \in Stack$ then
8	if <i>r</i> . <i>lowlink</i> $< \alpha$. <i>ca</i> then report "nonempty";
9	<i>r.lowlink</i> := min(<i>q.lowlink</i> , <i>r.ca</i>)
10	if q .lowlink = q .ca then
13	repeat $s := pop(Stack)$ until $s = q$

Javier Esparza Beyond Big-Oh analysis

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[GV04] requires only one post op per state.

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Space complexity

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Generalized Büchi automata

• LTL \rightarrow Büchi translations yield generalized BA.

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Generalized Büchi automata

- LTL \rightarrow Büchi translations yield generalized BA.
- GBA with *n* states and *k* acceptings sets → BA with *n* · *k* states. Expensive!
- Neither nested-DFS nor GV can be extended to GBA.

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- require less memory, and
- can be easily extended to GBAs?

First idea

Partition Stack into Roots and Nonroots, keeping the following invariant:

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- Key insight: *q* is a root iff it is a root of the part of the graph explored at time *ret*(*q*).
- So we can check if q is a root by checking q = top(Roots) at time ret(q).
- New problem: to keep the invariant.

GOD's contribution: oracle to keep the invariant

• For $q \rightarrow r$, the oracle decides if q reachable from $r: r \rightsquigarrow q$.

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- For $q \rightarrow r$, the oracle decides if q reachable from $r: r \rightsquigarrow q$.
- Observe: if $r \rightsquigarrow q$ then r belongs to a cycle.
- We show: no node in Roots discovered after r can be a root.

```
GCG(q)
1
2
      push(q, Roots);
3
      for each transition q \rightarrow r
4
         if r not yet explored then GCG(r)
5
         elseif r \rightsquigarrow q then
6
            repeat
7
               s :=pop(Roots); push(Nonroots);
8
               if s is accepting report "nonempty"
9
            until ca(s) \leq ca(r);
10
            push(s, Roots); pop(Nonroots)
      if top(Roots) = q then
11
12
         pop(Roots);
13
         while ca(top(Nonroots)) > ca(q)
            pop(Nonroots)
14
```





Time	Stack content
5	<i>q</i> ₄ <i>q</i> ₃ <i>q</i> ₂ <i>q</i> ₁ <i>q</i> ₀
6	$q_1 q_0$
8	$q_5 q_1 q_0$
9	$q_1 q_0$
10	$q_6 q_1 q_0$
12	$q_1 q_0$
14	ϵ

Correctness and optimality

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If *s* is popped at line 7, then it belongs to a cycle containing *r*.

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 Since *q* → *r* → *q*, we have *ρ_r* = *ρ_q*, and so *ρ_r* is a DFS-ascendant of *q*.

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 So either *ρ_r* is DFS-ascendant of *s* or vice versa.

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- *s* is a DFS-ascendant of *q*, and so $s \rightsquigarrow q$. Because $s \in Roots$, and Roots subset of DFS-stack.
- ρ_r is a DFS-ascendant of *s*, and so $\rho_r \rightsquigarrow s$. Since $q \rightarrow r \rightsquigarrow q$, we have $\rho_r = \rho_q$, and so ρ_r is a DFS-ascendant of *q*. So either ρ_r is DFS-ascendant of *s* or vice versa. But *s* cannot be a DFS-ascendant of ρ_r because $ca(\rho_r) \leq ca(r) < ca(s)$.

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Proof:

s belongs to a cycle containing r, and, since ca(s) > ca(r), it is not a root.

Every reachable state *q* belonging to some cycle is eventually popped at line 7.

Moreover, *q* is popped immediately after any cycle containing it is completely explored.

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- Fix a cycle *C* containing *q*.
- Let r be the last successor of q along C such that at time ca(q) there is a path of unexplored states from q to r (count q as unexplored, possibly q = r).

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- $ca(s) \leq ca(q) \leq ca(r)$, and so $ca(s) \leq ca(r)$.

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- $ca(s) \leq ca(q) \leq ca(r)$, and so $ca(s) \leq ca(r)$.
- So q is popped at line 7 when $q \rightarrow r$ is explored, or earlier.

Every state discovered by the search and not belonging to any cycle is eventually popped at line 12.

Proof:

Easy.
Lemma

Asume the oracle is asked at time *t* whether $r \rightsquigarrow q$. The answer is "yes" iff $t < ret(\rho_r)$.

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- Situation: $ca(q) \le t < ret(q), q \rightarrow r, ca(r) \le t$.
- Assume $r \rightsquigarrow q$. If $t \ge ret(\rho_r)$, then $t \ge ret(q)$, contradiction. So $t < ret(\rho_r)$

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• Assume
$$r \not\rightarrow q$$
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- Assume $r \not\rightarrow q$. Then $q \rightsquigarrow \rho_r \not\rightarrow q$. By postorder lemma, $ret(\rho_r) < ret(q)$.

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- Assume $r \nleftrightarrow q$. Then $q \rightsquigarrow \rho_r \nleftrightarrow q$. By postorder lemma, $ret(\rho_r) < ret(q)$. Case 1: $ca(\rho_r) < ret(\rho_r) < ca(q) \le t < ret(q)$. Done.

Lemma

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- Situation: $ca(q) \leq t < ret(q), q \rightarrow r, ca(r) \leq t$.
- Assume $r \rightsquigarrow q$. If $t \ge ret(\rho_r)$, then $t \ge ret(q)$, contradiction. So $t < ret(\rho_r)$

• Assume
$$r \nleftrightarrow q$$
. Then $q \rightsquigarrow \rho_r \nleftrightarrow q$.
By postorder lemma, $ret(\rho_r) < ret(q)$.
Case 1: $ca(\rho_r) < ret(\rho_r) < ca(q) \le t < ret(q)$. Done
Case 2: $ca(q) < ca(\rho_r) \le ca(r) < ret(\rho_r) < ret(q)$.
Since at time *t* we are executing $dfs(q)$, we have
 $ret(\rho_r) < t \le ret(q)$.

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Idea

- Recall $ca(r) \leq t$.
- At time *ret*(ρ) removes all nodes from ρ's SCC from Rots and Nonroots.
- So r stays in Stack exactly during the interval [ca(r), ret(root(t))], and therefore:

Lemma

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Idea

- Recall $ca(r) \leq t$.
- At time *ret*(ρ) removes all nodes from ρ's SCC from Rots and Nonroots.

So *r* stays in Stack exactly during the interval [*ca*(*r*), *ret*(*root*(*t*))], and therefore:
 t < *ret*(ρ_r) iff *r* ∈ *Roots* ∪ *Nonroots* at time *t*.

Couvrer and Gabow's algorithm [C99,G00]

1	GCG(q)
2	push(<i>q</i> , <i>Roots</i>);
3	for each transition $q \rightarrow r$
4	if <i>r</i> not yet explored then GCG(<i>r</i>)
5	elseif <i>r</i> ∈ <i>Roots</i> ∪ <i>Nonroots</i> then
6	repeat
7	<pre>s :=pop(Roots); push(Nonroots);</pre>
8	if <i>s</i> is accepting report "nonempty"
9	until $ca(s) \leq ca(r);$
10	push(<i>s</i> , <i>Roots</i>); pop(<i>Nonroots</i>)
11	if $top(Roots) = q$ then
12	pop(<i>Roots</i>);
13	while <i>ca</i> (<i>top</i> (<i>Nonroots</i>)) > <i>ca</i> (<i>q</i>)
14	pop(<i>Nonroots</i>)

Extension to generalized Büchi automata

Store for each state $q \in Roots$ a subset q.acc of accepting sets, maintaining the following invariant:

 q.acc contains all the accepting sets intersecting q's SCC in the part of the graph explored so far.

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When GC(q) pops a cycle, add all the *acc*'s of the popped states to *q*.*acc*.

1	EGC(q)
2	push(<i>q</i> , <i>Roots</i>);
3	q.acc := accepting sets containing q;
4	for each transition $q \rightarrow r$
5	if r not yet explored then EGC(r)
6	elseif $r \in Roots \cup Nonroots$ then
7	repeat
8	<pre>s :=pop(Roots); push(s, Nonroots);</pre>
9	$q.acc := q.acc \cup s.acc$
10	until $ca(s) \leq ca(r);$
11	push(<i>s</i> , <i>Roots</i>); pop(<i>Nonroots</i>);
12	if <i>q.acc</i> = all accepting sets report "nonempty"
13	if $q = top(Roots)$ then
14	pop(<i>Roots</i>);
15	while $ca(top(Nonroots)) > ca(q)$
16	pop(<i>Nonroots</i>)

The SCC of a root can also be determined as follows:

- Introduce one extra bit b_q for every state q. Initially $b_q = 0$.
- For every root ρ: at time ret(ρ) conduct a DFS to set to 1 the bits of all states reachable from ρ.
- The set of states that had to be flipped constitute ρ 's SCC.

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- Introduce one extra bit b_q for every state q. Initially $b_q = 0$.
- For every root ρ: at time ret(ρ) conduct a DFS to set to 1 the bits of all states reachable from ρ.
- The set of states that had to be flipped constitute ρ 's SCC. Gets rid of Nonroots, but requires one extra DFS.

End of the story? No!

Černá and Pelánek's observation [ČP03]

- Many LTL specifications are translated into weak Büchi automata.
- The four-colour algorithm without the second search is correct for weak automata.

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Schwoon and E. [SE05]

The four-colour algorithm without the second searches is optimal for weak automata.

End of the story?

	Nested-DFS	SCC-based
Time	2 post ops	1/2 post op
Space	2 bits	2/1 numbers
Optimal	Only for WBA	Yes
Ext. to GBA	No	Yes

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Ext. to GBA	No	Yes

Practical relevance of differences in space complexity

- Small when state descriptors explicitly stored. (state descriptors are often dozens of bytes long)
- Large when state-hashing is applied. (one or two bits for storing a state)

• Are there optimal algorithms requiring only a constant number of additional bits per state?

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- Are there algorithms for GBA requiring only a constant number of additional bits per state?
- Can a shortest counterexample be computed in linear time?

Universal search

Javier Esparza Beyond Big-Oh analysis

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Let A[x] be an algorithm computing F(x) in f(n) time.
 A is optimal for F if no other algorithm computes F in o(f(n)) time.

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- Let A[x] be an algorithm computing F(x) in f(n) time.
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- Let A[x] be an algorithm computing F(x) in f(n) time.
 A is optimal for F if no other algorithm computes F in o(f(n)) time.
- We give a universal algorithm that is optimal for every *F*.
- Corollary: if constants don't matter we are all useless!

A bit more formally ...

- Fix a formal system (i.e., ZF).
- A function is provably computable if some algorithm computes it and the algorithm's correctness is a theorem of the system.

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Theorem (Levin)

There is an algorithm U[F, x] such that U[F, -] is optimal for every provably computable function F.

A non-optimal algorithm $U_1[F, -]$

We describe first an obviously correct algorithm $U_1[F, -]$. On input *x*, $U_1[F, -]$ behaves as follows:

- U₁[F, -] enumerates all pairs Π = (P, D), where P program and D derivation of the formal system. Let Π₁, Π₂, Π₃... be this enumeration.
- For every Π_i = (P_i, D_i): U₁[F, -] checks if D_i is a proof that P_i computes F. If so, U₁[F, -] computes P_i[x] and stops.

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The algorithm U[F, -]

U[F, x] dovetails the computations of $U_1[F, -]$. It spends:

- every second step on Π_1 ;
- every second step of the remaining ones on Π_2 ;
- every second step of the remaining ones on Π_3 , etc.

Claim

If P runs in f(n) time, then U[F, -] runs in O(f(n)) time.

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Proof idea:

Let *i* be the smallest index such that $P_i = P$ and D_i proves that *P* computes *F*. (Observe: *i* independent of *x*!)
If P runs in f(n) time, then U[F, -] runs in O(f(n)) time.

Proof idea:

Let *i* be the smallest index such that $P_i = P$ and D_i proves that *P* computes *F*. (Observe: *i* independent of *x*!) Then U[F, -] terminates on input *x* after executing f(x) steps of Π_i , or earlier.

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Total number of steps executed by U[F, -] on x:

So U[F, -] takes at most $2^{i+1} \cdot f(x) = O(f(x))$ steps.

If P runs in f(n) time, then U[F, -] runs in O(f(n)) time.

Proof idea:

Let *i* be the smallest index such that $P_i = P$ and D_i proves that *P* computes *F*. (Observe: *i* independent of *x*!)

Then U[F, -] terminates on input *x* after executing f(x) steps of Π_i , or earlier.

Total number of steps executed by U[F, -] on x:

• Steps spent on
$$\Pi_i, \Pi_{i-1}, \dots, \Pi_1$$
:
 $f(x) + 2f(x) + 2^2f(x) + \dots + 2^if(x) = (2^{i+1} - 1)f(x)$

So U[F, -] takes at most $2^{i+1} \cdot f(x) = O(f(x))$ steps.

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- Steps spent on $\Pi_{i+1}, \Pi_{i+2}, \ldots$: $\frac{1}{2}f(x) + \frac{1}{4}f(x) + \ldots + 1 \le f(x) = f(x)$

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Conclusions

Javier Esparza Beyond Big-Oh analysis

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- It is not only about heuristics and hacking: good theory is waiting for us there.