



A Fresh Look at Linear Temporal Logic

Javier Esparza

Technical University of Munich

Joint work with Jan Křetínský and Salomon Sickert



Logic

Logic

If all bandersnatches are borogoves
and all borogoves are slithy,
then all bandersnatches are slithy.

Logic

If all bandersnatches are borogoves
and all borogoves are slithy,
then all bandersnatches are slithy.

„True“

Logic

If all X are Y and
all Y are Z ,
then all X are Z .

Logic

Logic is the subject of identifying true statements in a language of which you only know a few words.

Temporal Logic

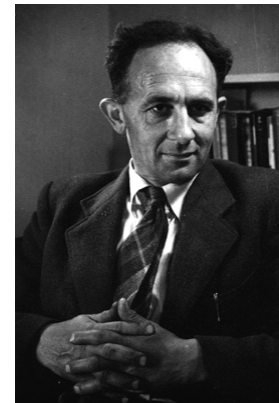
Different logics study different language fragments:

- Propositional logic: and, or, not, if ... then
- Temporal logic: propositional logic + today, tomorrow, eventually, never, ...

Studied within mathematical logic since the end of the XIX century.



Clarence Lewis
(1883-1964)



Arthur Prior
(1914-1969)

Temporal logic in computer science

- Amir Pnueli proposes in 1977 to use temporal logic to reason about computer programs



אמיר פנואלי
Amir Pnueli
(1941-2009)
Turing Award 1996

THE TEMPORAL LOGIC OF PROGRAMS*
Amir Pnueli
University of Pennsylvania, Pa. 19104
and
Tel-Aviv University, Tel Aviv, Israel

Summary:

A unified approach to program verification is suggested, which applies to both sequential and parallel programs. The main proof method suggested is that of temporal reasoning in which the time dependence of events is the basic concept. Two formal systems are presented for providing a basis for temporal reasoning. One forms a formalization of the method of intermittent assertions, while the other is an adaptation of the tense logic system K_b , and is particularly suitable for reasoning about concurrent programs.

Temporal logic in computer science

A worker that succeeds in acquiring a lock will **eventually** release it, assuming its "doResult" call returns.

The req_close_state is **always** in close_enabled state.

If artist1 registers for event2 **before** artist2 does, then **once** dispatcher receives event2 from the ADT, it will **first** send it to artist1 **and then** to artist2.

The OK button on the login window is enabled **as soon as** the application is started and the login window is **first** displayed to the user.

None of the available methods can be called **until** connect is called.

Linear Temporal Logic (LTL)

- LTL extends propositional logic with temporal operators.
- Syntax:

$\varphi := \mathbf{true} \mid \mathbf{false} \mid p \mid \neg p \mid \varphi_1 \wedge \varphi_2 \mid \varphi_1 \vee \varphi_2$

$\mathbf{X}\varphi_1 \mid \varphi_1 \mathbf{U}\varphi_2 \mid \varphi_1 \mathbf{W}\varphi_2$

$\varphi_1 \mathbf{R}\varphi_2 \mid \varphi_1 \mathbf{M}\varphi_2 \mid$ past operators (Past LTL)

$\mathbf{F}\varphi := \mathbf{true} \mathbf{U} \varphi$ (eventually φ or finally φ).

$\mathbf{G}\varphi := \varphi \mathbf{W} \mathbf{false}$ (always φ or globally φ).

Temporal logic in computer science

A worker that succeeds in acquiring a lock will **eventually** release it, assuming its "doResult" call returns.

$$\mathbf{G}(\text{call}_{\text{doResult}} \rightarrow \mathbf{F} \text{return}_{\text{doResult}}) \rightarrow \mathbf{G}(\text{return}_{\text{lockacq}} \rightarrow \mathbf{F} \text{call}_{\text{lockrel}})$$

If artist1 registers for event **before** artist2 does, then **once** dispatcher receives event from the ADT, it will **first** notify artist1 **and then** artist2.

$$\mathbf{G}((\text{reg. } a_1 \wedge (\neg \text{unreg. } a_1 \mathbf{U} (\text{reg. } a_2 \wedge (\neg \text{unreg. } a_1 \wedge \neg \text{unreg. } a_2) \mathbf{U} \text{notify})))) \rightarrow \mathbf{F} (\text{notify} \wedge (\neg \text{notify. } a_2 \mathbf{U} \text{notify. } a_1)))$$

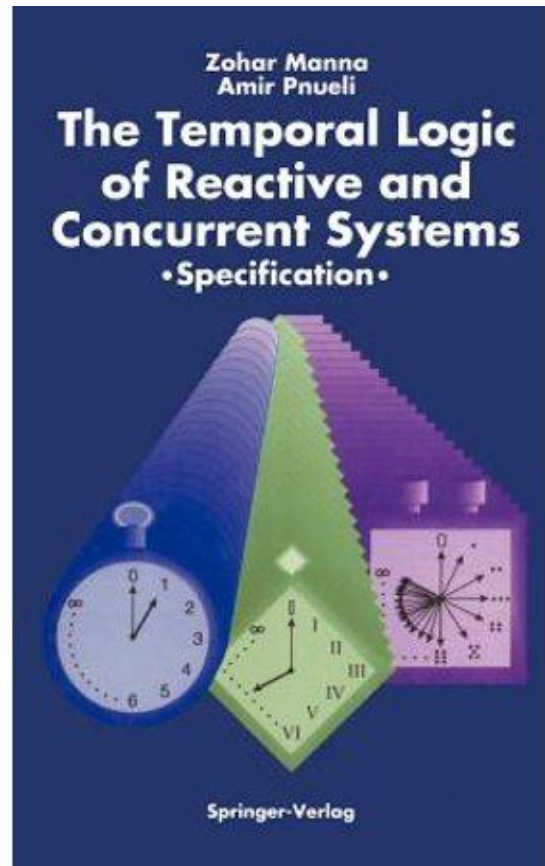
Specifying and verifying reactive systems



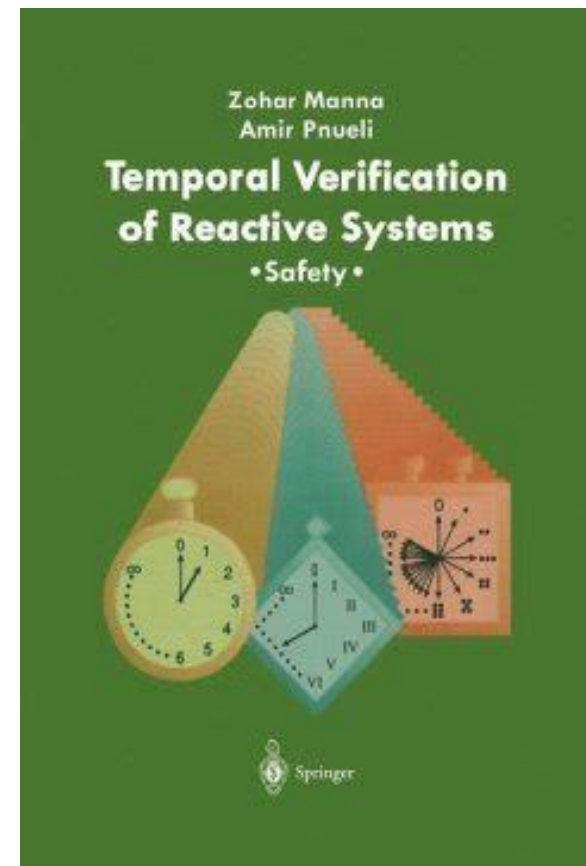
זוהר מנה
Zohar Manna
(1939-2018)



אמיר פנואלי
Amir Pnueli
(1941-2009)

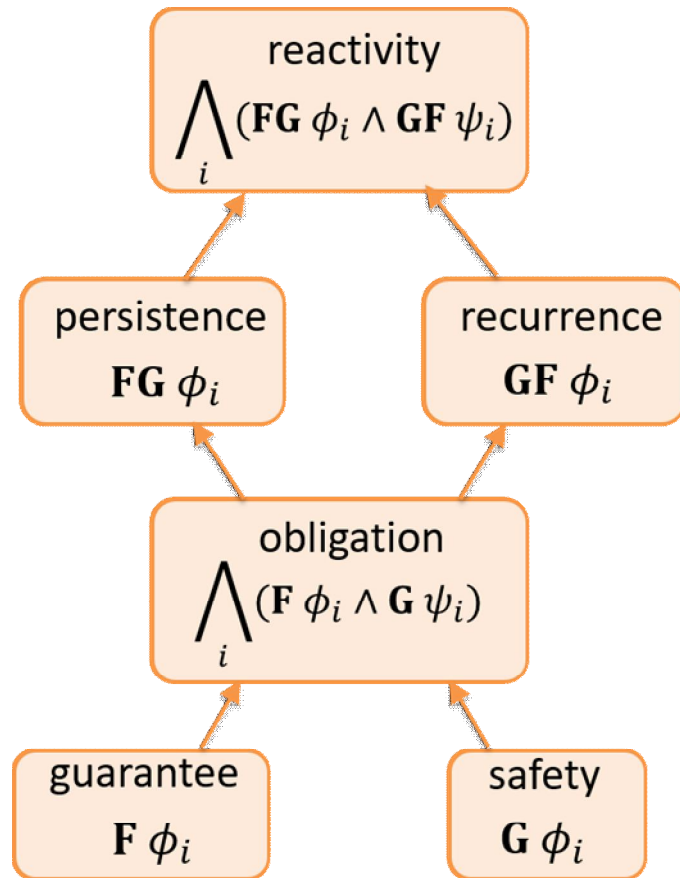


1992



1995

The Safety-Progress Hierarchy



ϕ_i and ψ_i
are **past formulas**

Proof rules for different classes
in the hierarchy:

$$I1. \quad \Theta \rightarrow \varphi$$

$$I2. \quad \varphi \rightarrow q$$

$$I3. \quad \{\varphi\} \mathcal{T} \{\varphi\}$$

$$\square q$$

$$C1. \quad \square(p \rightarrow (q \vee \varphi))$$

$$C2. \quad \{\varphi\} \mathcal{T} \{q \vee \varphi\}$$

$$C3. \quad \{\varphi\} \tau \{q\}$$

$$C4. \quad \mathcal{T} - \{\tau\} \vdash \square(\varphi \rightarrow \diamond(q \vee En(\tau)))$$

$$\square(p \rightarrow \diamond q)$$

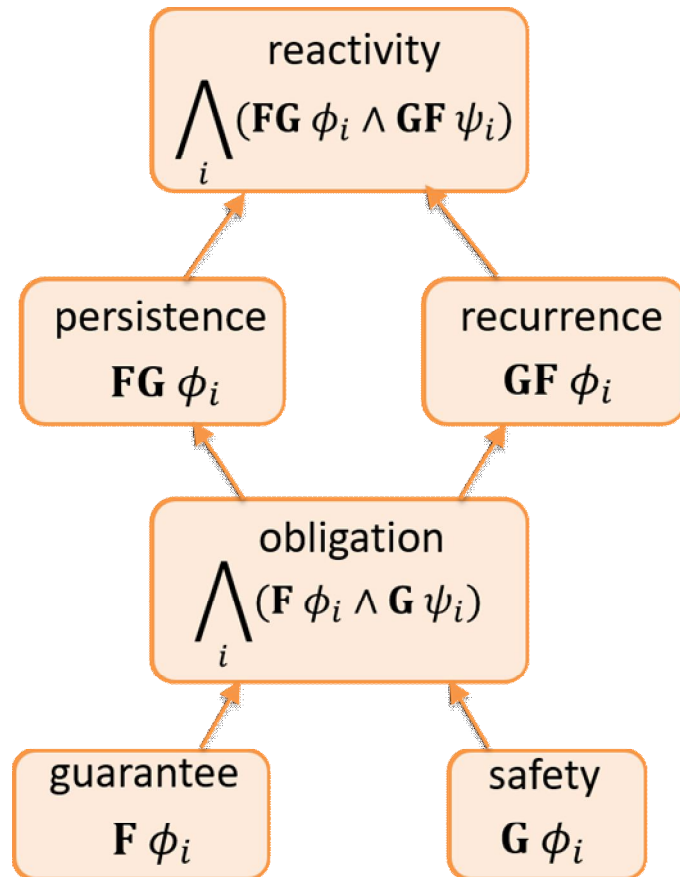
$$B1. \quad \square(p \rightarrow (q \vee \varphi))$$

$$B2. \quad \{\varphi \wedge (\delta = \alpha)\} \mathcal{T} \{q \vee (\varphi \wedge (\delta \preceq \alpha))\}$$

$$B3. \quad \square([\varphi \wedge (\delta = \alpha) \wedge r] \rightarrow \diamond[q \vee (\delta \prec \alpha)])$$

$$\square((p \wedge \square \diamond r) \rightarrow \diamond q)$$

The Safety-Progress Hierarchy



ϕ_i and ψ_i
are **past formulas**

Normal form theorem
Every formula is equivalent
to a reactivity formula.

Proving the Normal Form Theorem

The Glory of The Past

Orna Lichtenstein
Dept. of Computer Science
Tel Aviv University
Ramat Aviv, Israel

Amir Pnueli
and
Lenore Zuck*
Dept. of Applied Mathematics
The Weizmann Institute of Science
Rehovot, 76100 Israel

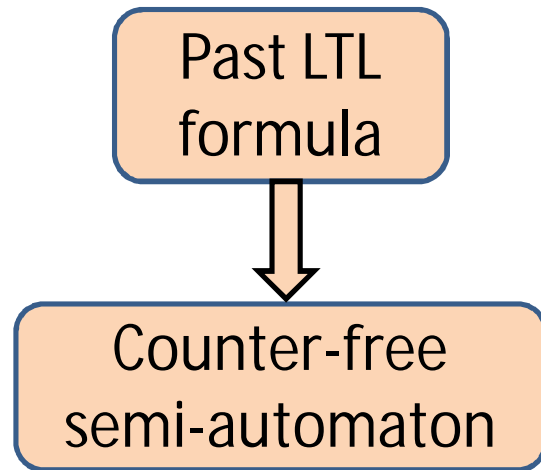
„The proof [...] is based on many previous results, including [Buc], [MNP], [C], [T] and [GPSS] which, when combined, yield the theorems almost immediately.“

Proving the Normal Form Theorem

Past LTL
formula

Zuck, PhD Thesis, 1986

Proving the Normal Form Theorem

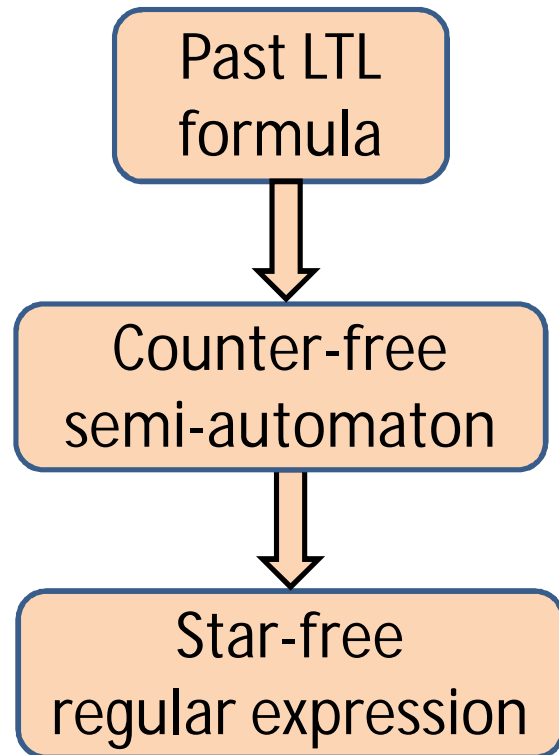


Zuck, PhD Thesis, 1986

Chapter 4

Proving the Normal Form Theorem

Zuck, PhD Thesis, 1986

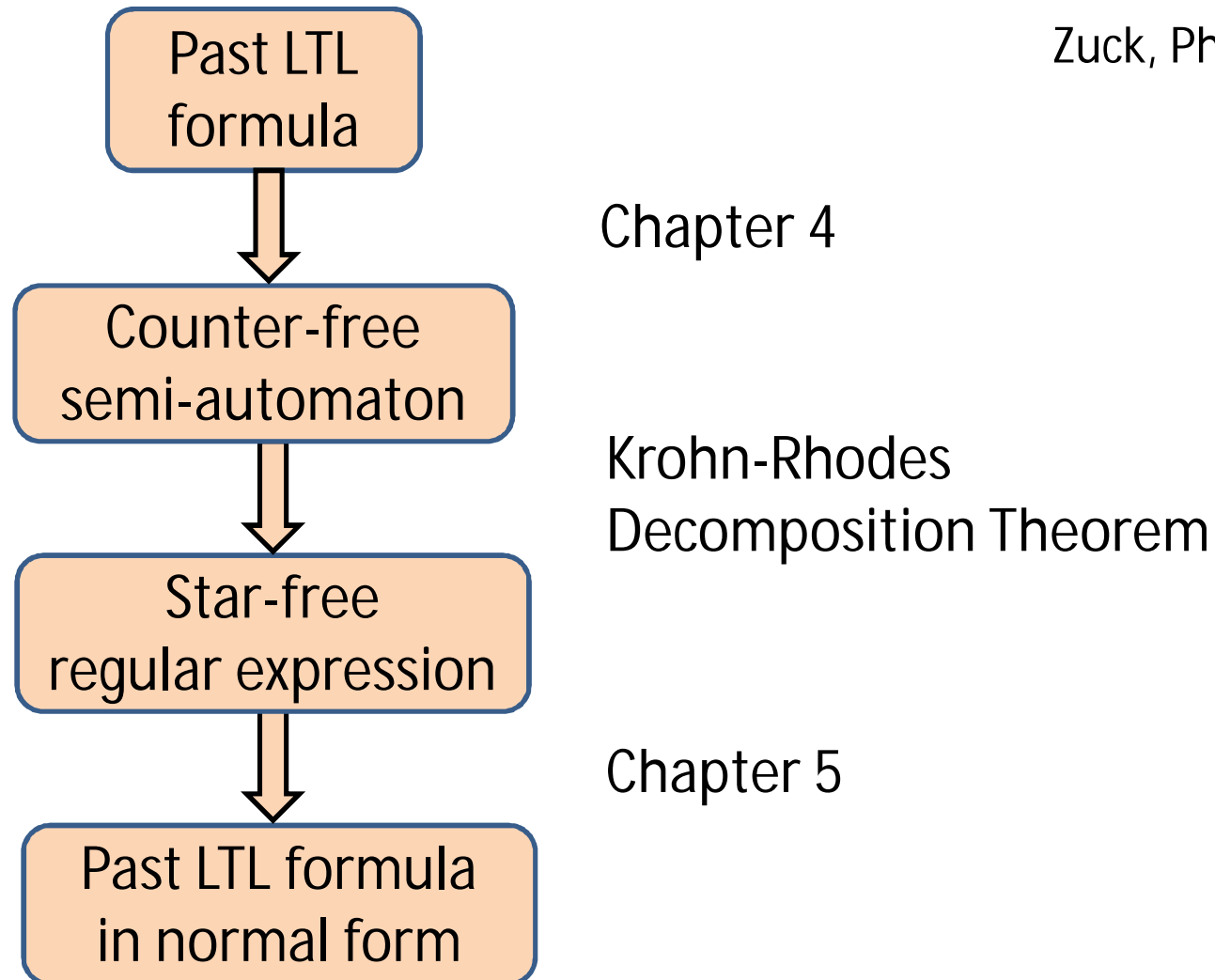


Chapter 4

Krohn-Rhodes
Decomposition Theorem

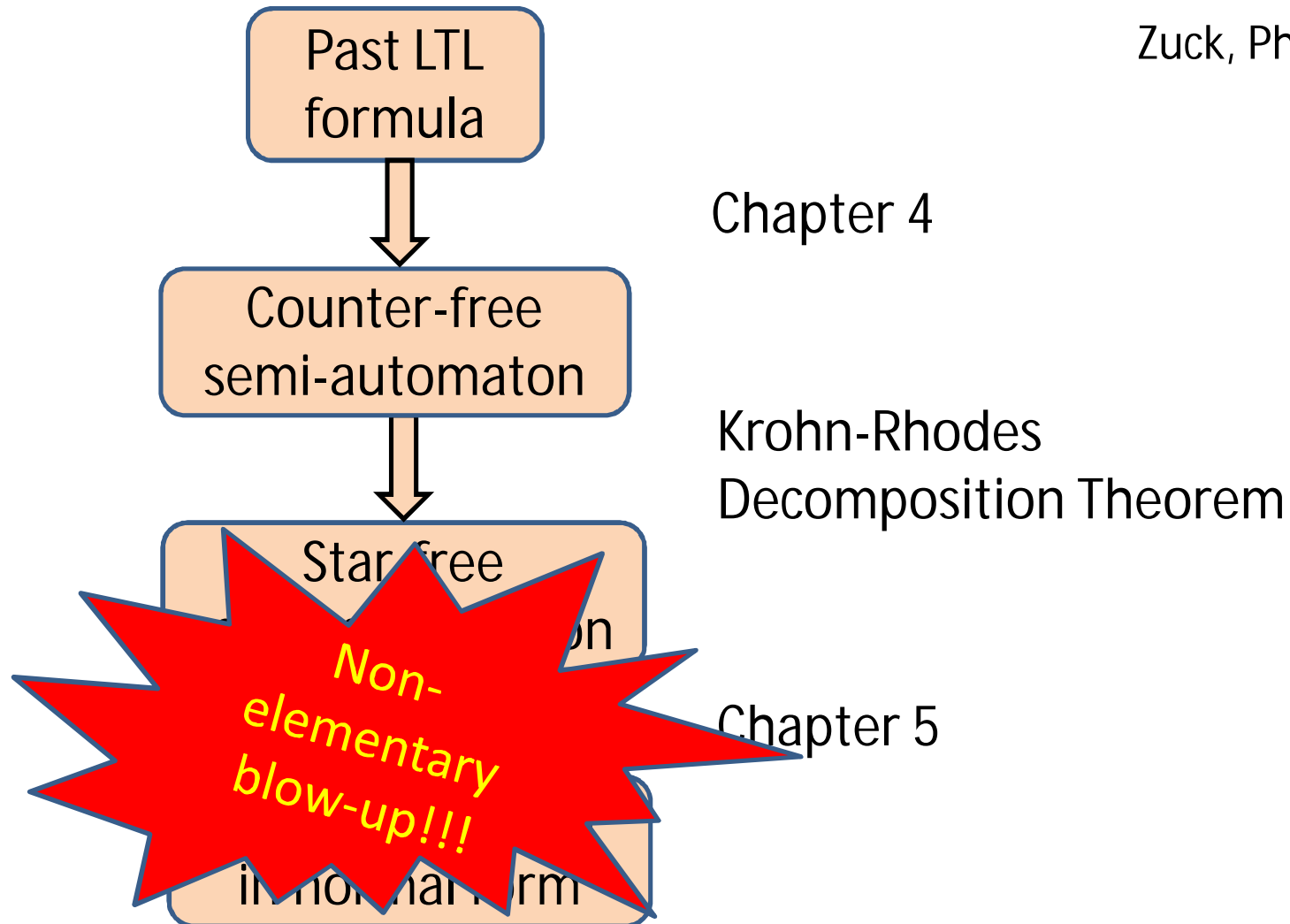
Proving the Normal Form Theorem

Zuck, PhD Thesis, 1986

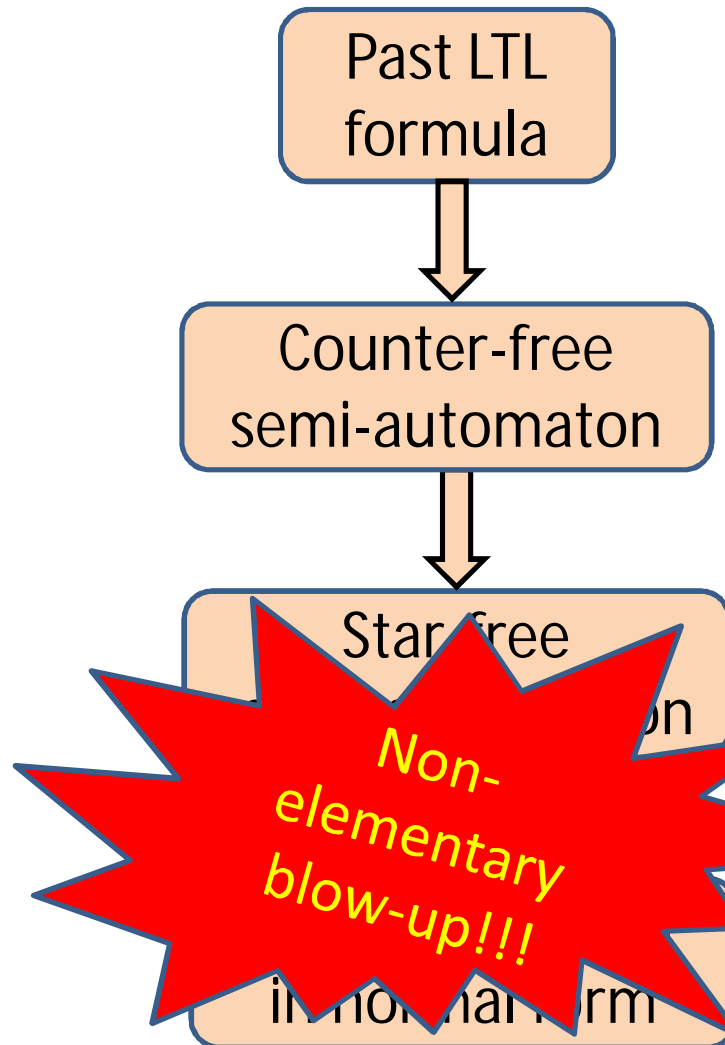


Proving the Normal Form Theorem

Zuck, PhD Thesis, 1986



Proving the Normal Form Theorem



Zuck, PhD Thesis, 1986

Chapter 4

Krohn-Rhodes Decomposition



Chapter 5

Maler, Essays in Memory of Amir Pnueli, 2010

... and the rest is silence.

No further attempts to improve on these bounds, even though there is no lower bound!

How come?

... and the rest is silence.

No further attempts to improve on these bounds, even though there is no lower bound!

An Automata-Theoretic Approach to Automatic Program Verification



Moshe Y. Vardi

CSLI, Ventura Hall,
Stanford University,
Stanford, CA 94305.



Pierre Wolper

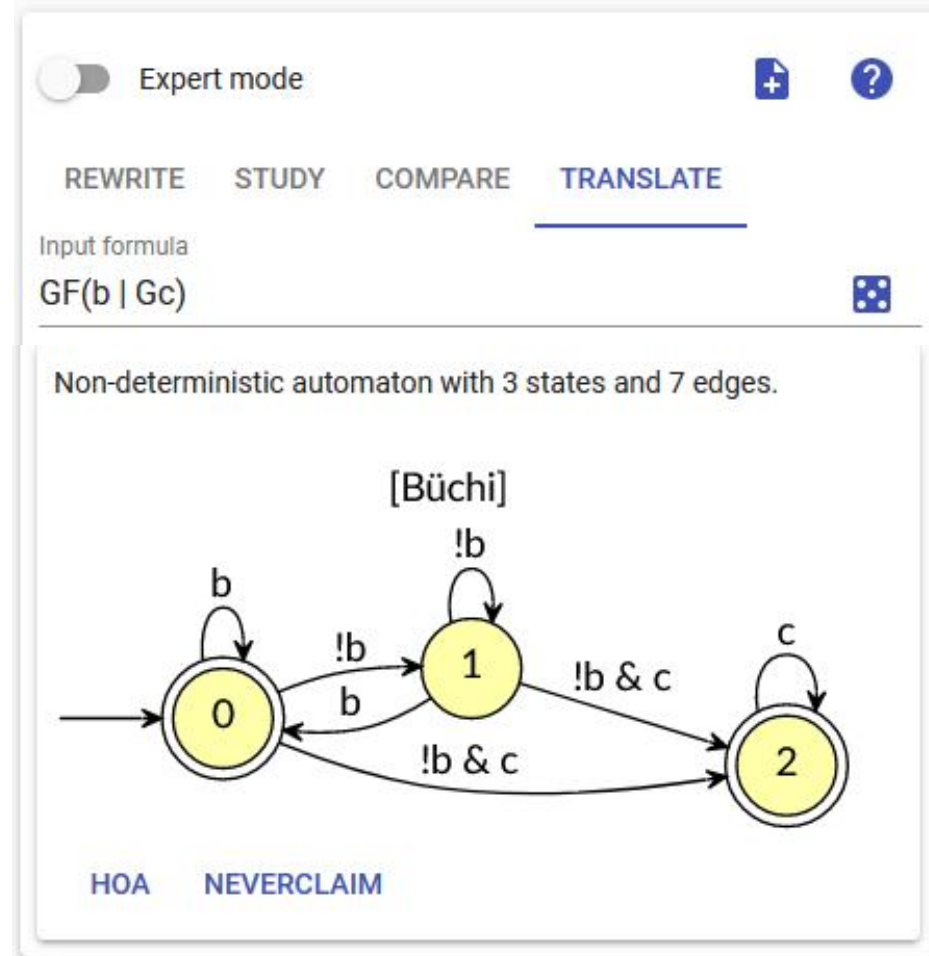
AT&T Bell Laboratories
600 Mountain Ave.
Murray Hill, NJ 07974

Gödel Prize
2000

LICS '86

Automata-theoretic approach

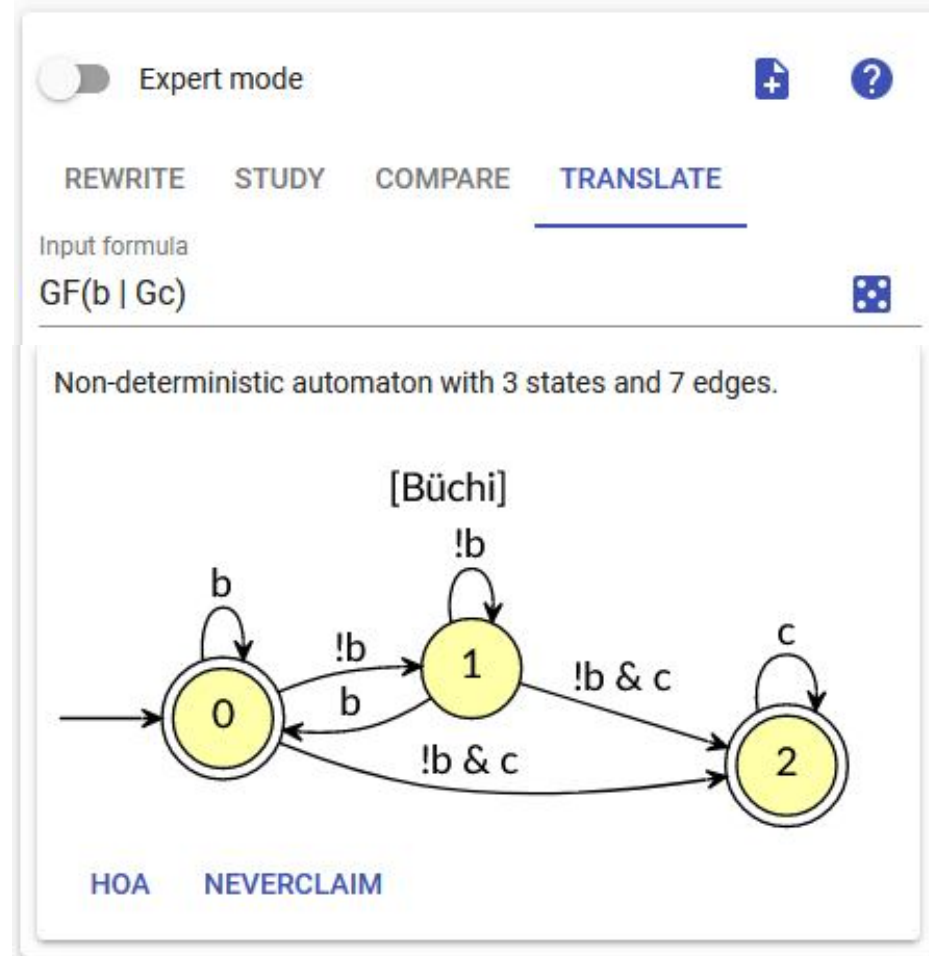
- Translates the formula into an ω -automaton (automaton on infinite words) and „throws the formula away“
- Proofs replaced by automata-theoretic algorithms
- No need for hierarchies, proof rules, or axiom systems



Duret-Lutz: Spot Online Translator
<https://spot.lrde.epita.fr/app/>

Automata-theoretic approach

- Translates the formula into an ω -automaton (automaton on infinite words) and „throws the formula away“
- Proofs replaced by automata-theoretic algorithms
- No need for hierarchies, proof rules, or axiom systems
- **LTL „demoted“ to syntax for automata**



Duret-Lutz: Spot Online Translator
<https://spot.lrde.epita.fr/app/>

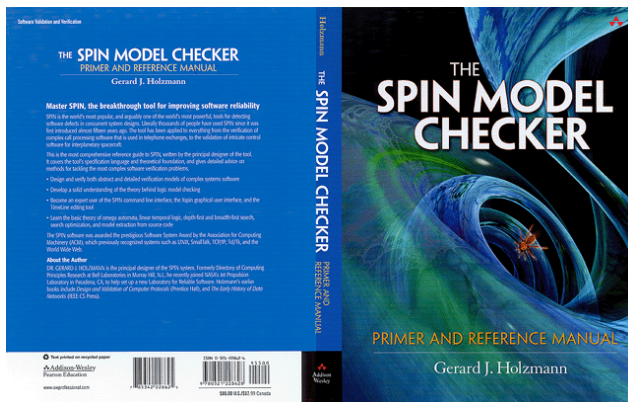
Automata-theoretic approach

During the next decades the automata-theoretic approach

Automata-theoretic approach

During the next decades the automata-theoretic approach

- is implemented in sophisticated, very successful tools

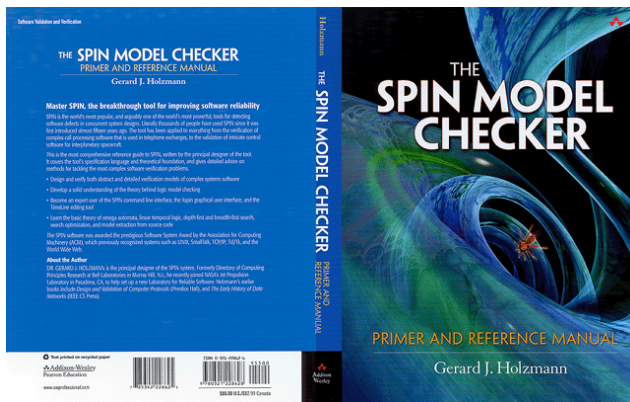


2004

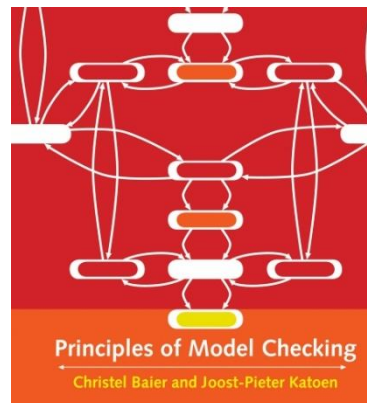
Automata-theoretic approach

During the next decades the automata-theoretic approach

- is implemented in sophisticated, very successful tools
- is extended to the **verification of probabilistic systems**



2004

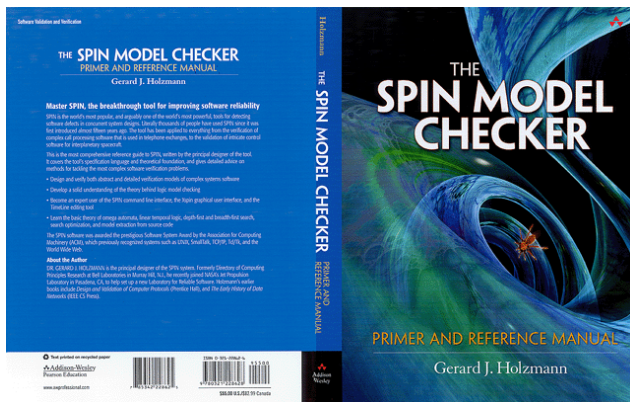


2008

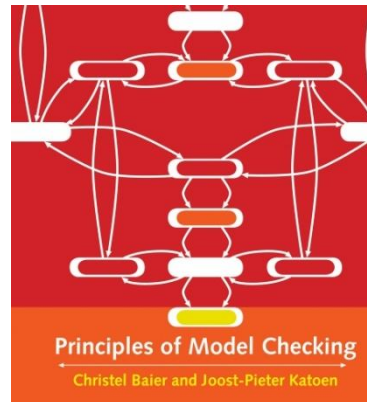
Automata-theoretic approach

During the next decades the automata-theoretic approach

- is implemented in sophisticated, very successful tools
- is extended to the **verification of probabilistic systems**
- is applied to **reactive synthesis**: automatic synthesis of reactive systems from LTL specifications



2004



2008

The Reactive Synthesis Competition

www.syntcomp.org

Menu

General Information

The Reactive Synthesis Competition (SYNTCOMP) is a competition for reactive synthesis tools. The competition's goal is to [collect benchmarks in a publicly available library](#) and foster research in new tools for automatic synthesis of systems. SYNTCOMP is organized annually (since 2014) as a satellite event of [CAV](#).

2014-today

The challenge

- Reactive synthesis requires to translate LTL into **deterministic** ω -automata
- Probabilistic verification requires to translate LTL into **limit deterministic** (or deterministic) ω -automata

The theoretical challenge



On The Complexity of ω -Automata*

Shmuel Safra

Department of Applied Mathematics
Weizmann Institute of Science
Rehovot 76100, Israel

FOCS 1988: Determinization procedure for ω -automata



The Complexity of Probabilistic Verification

COSTAS COURCOUBETIS

University of Crete, and ICS, Farth, Heraklion, Greece

AND

MIHALIS YANNAKAKIS

AT&T Bell Laboratories, Murray Hill, New Jersey

(see also
Vardi 1985)

JACM 1995: Limit-determinization procedure for ω -automata

The algorithmic challenge

These translations

- have **double-exponential** blow-up.
(contrary to single-exponential for LTL \rightarrow nondet. automata)
- are „**monolithic**“ and very combinatorial
e.g. states of Safra's det. automaton are
trees of sets of states of the nondet. automaton

\Rightarrow

Implementations struggle to control
combinatorial explosion

The algorithmic challenge

$$\bigwedge_{i=1}^j (\mathbf{GF}a_i) \implies \bigwedge_{i=1}^j (\mathbf{GF}b_i)$$

$$k: \bigwedge_{i=1}^k (\mathbf{GF}a_i \vee \mathbf{FG}b_i)$$

$$f(0, j) = (\mathbf{GF}a_0) \mathbf{U}(\mathbf{X}^j b)$$

$$f(i + 1, j) = (\mathbf{GF}a_{i+1}) \mathbf{U}(\mathbf{G}f(i, j))$$

Safra
(spot+l2dstar)

$j = 1$	5
$j = 2$	17
$j = 3$	49
$j = 4$	129
<hr/>	
$k = 2$	4385
$k = 3$	*
<hr/>	
$f(0, 0)$	5
$f(0, 2)$	10
$f(0, 4)$	12
$f(1, 0)$	196
$f(1, 2)$	109839
$f(1, 4)$	*
$f(2, 0)$	99793
$f(2, 2)$	*
$f(2, 4)$	*

How can I do better in the future?



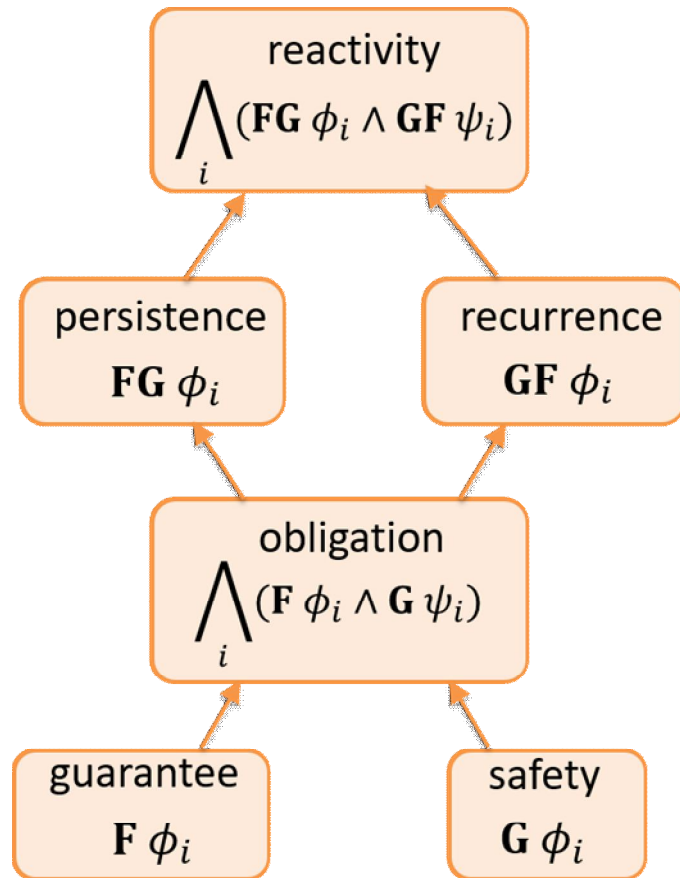
How can I do better in the future?



Do better in the past!

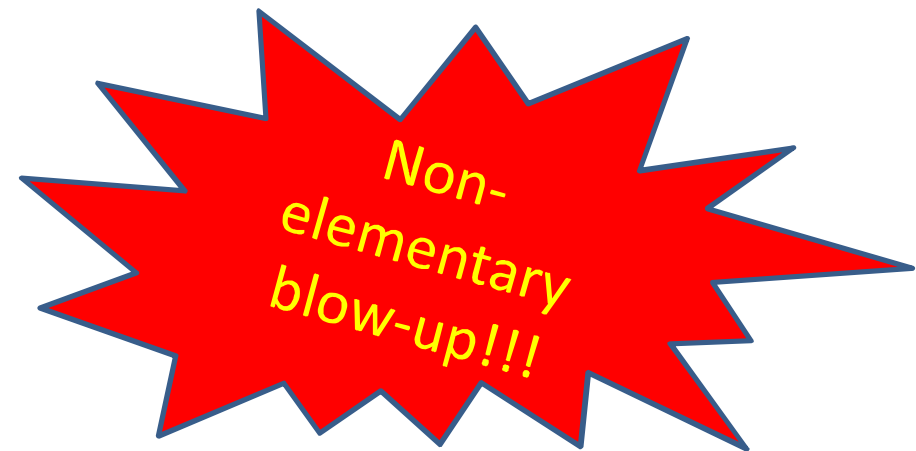


Back to the 1980s: The Safety-Progress Hierarchy

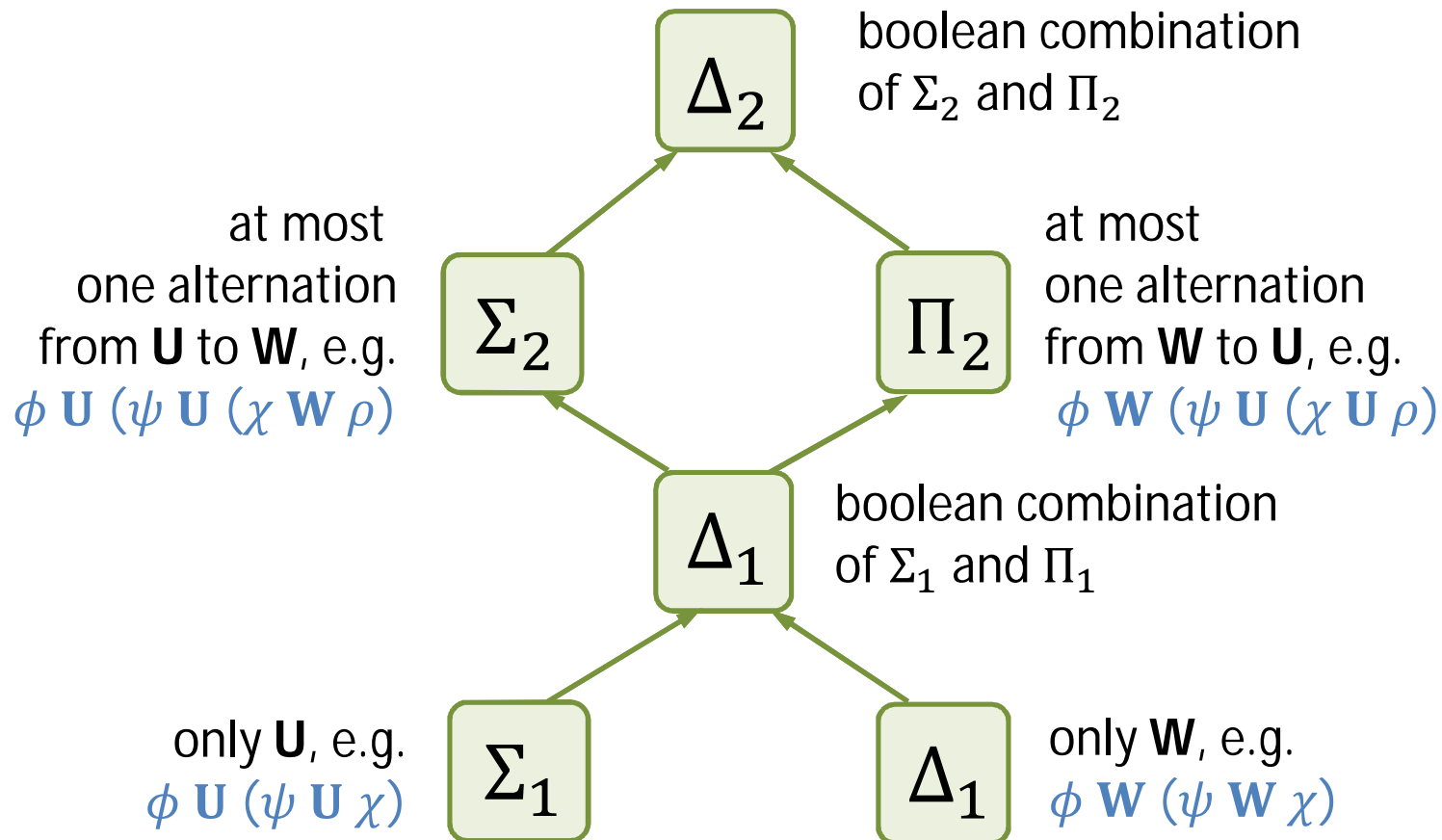


ϕ_i and ψ_i
are **past formulas**

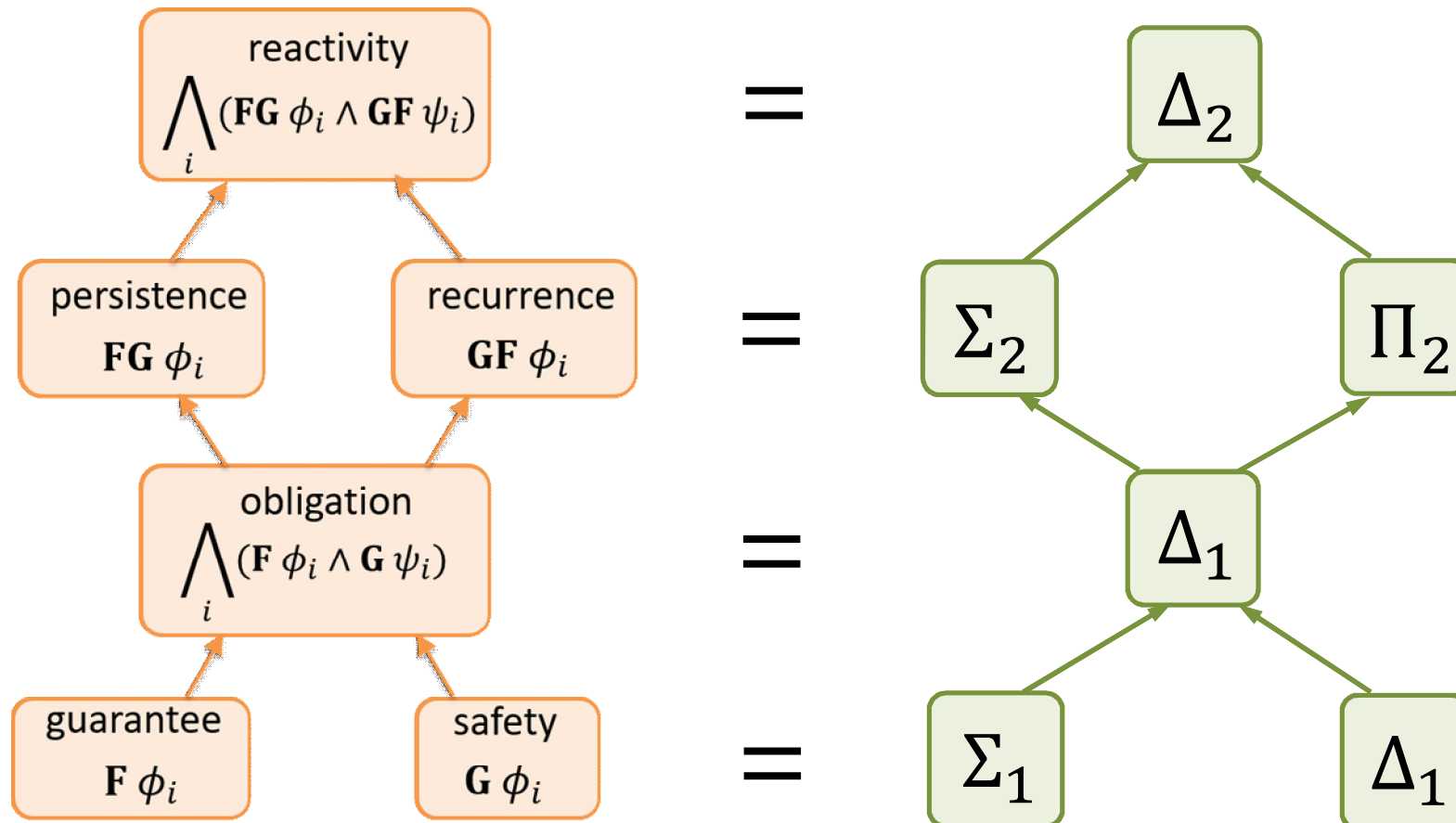
Normal form theorem
Every formula is equivalent
to a reactivity formula.



The Alternation Hierarchy



The Alternation Hierarchy

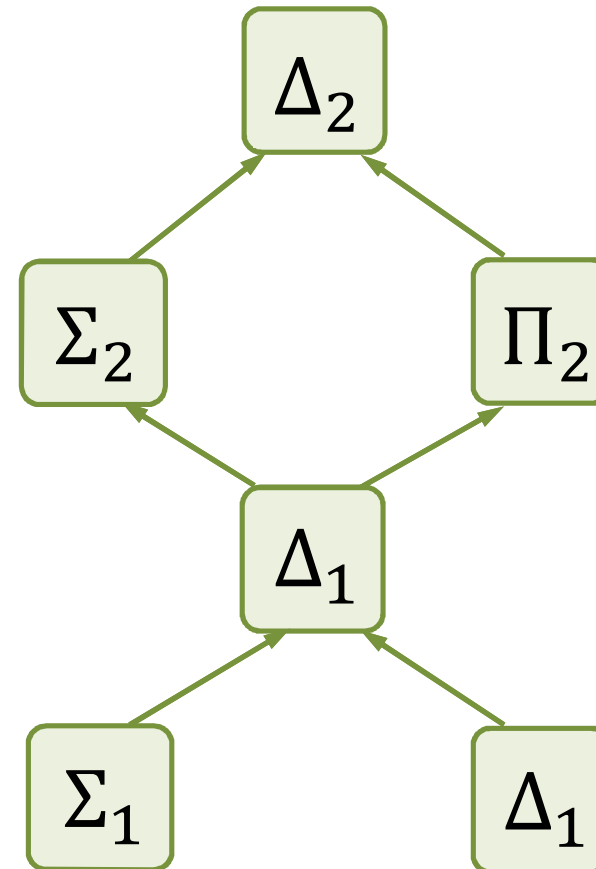
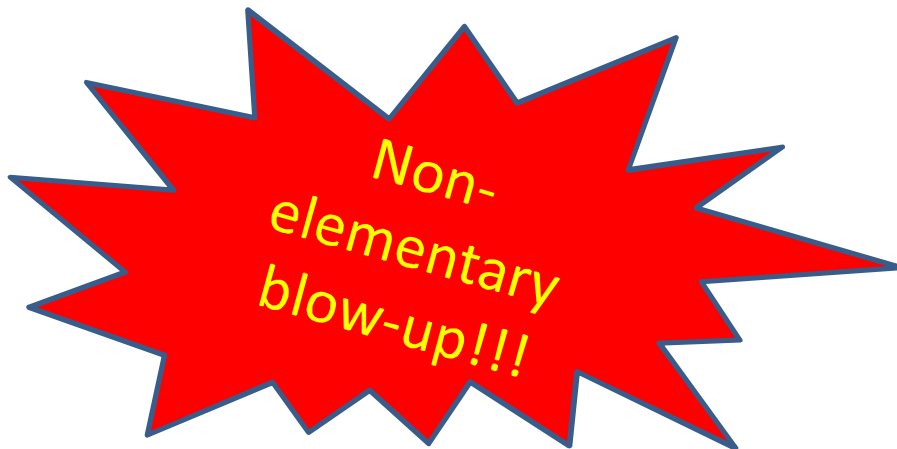


Chang, Manna, and Pnueli, ICALP 1992.
 Pelánek and Strejček, CIAA 2005

The Alternation Hierarchy

Normal form theorem

Every formula is equivalent to a Δ_2 -formula.



Demystifying normalization

$$\mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c))$$

Demystifying normalization

$$\mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c))$$

Demystifying normalization

$$\mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c))$$

Case 1: $\mathbf{F}c$ holds infinitely often ($\mathbf{G}\mathbf{F}c$ holds)

Case 2: $\mathbf{F}c$ only holds finitely often ($\neg\mathbf{G}\mathbf{F}c$ holds)

Demystifying normalization

$$\mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c))$$

Case 1: $\mathbf{F}c$ holds infinitely often ($\mathbf{G}\mathbf{F}c$ holds)

Then $\mathbf{G}(b \vee \mathbf{F}c) \equiv^{\mathbf{G}\mathbf{F}c} \mathbf{true}$

Case 2: $\mathbf{F}c$ only holds finitely often ($\neg\mathbf{G}\mathbf{F}c$ holds)

Demystifying normalization

$$\mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c))$$

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Then $\mathbf{G}(b \vee \mathbf{F}c) \equiv^{\mathbf{G}\mathbf{F}c} \mathbf{true}$

Case 2: $\mathbf{F}c$ only holds finitely often ($\neg\mathbf{G}\mathbf{F}c$ holds)

Then $\mathbf{G}(b \vee \mathbf{F}c) \equiv^{\neg\mathbf{G}\mathbf{F}c} (b \vee \mathbf{F}c) \mathbf{U} (\mathbf{G}b)$

Demystifying normalization

$$\mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c))$$

Case 1: Fc holds infinitely often (GFc holds)

Then $\mathbf{G}(b \vee \mathbf{F}c) \equiv^{GFc} \mathbf{true}$

Case 2: Fc only holds finitely often ($\neg GFc$ holds)

Then $\mathbf{G}(b \vee \mathbf{F}c) \equiv^{\neg GFc} (b \vee \mathbf{F}c) \mathbf{U}(\mathbf{G}b)$

WU \rightarrow UW !!



Demystifying normalization

$$\mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c))$$

Demystifying normalization

$$\mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c)) \equiv \mathbf{GF}c \wedge \mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c)) \vee \neg \mathbf{GF}c \wedge \mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c))$$

Demystifying normalization

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Demystifying normalization

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Correct because **GFc**
holds at some moment
iff it holds at every moment!



Demystifying normalization

$$\mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c)) \equiv \mathbf{GF}c \wedge \mathbf{F}(a \wedge \mathbf{true}) \\ \vee \\ \neg \mathbf{GF}c \wedge \mathbf{F}(a \wedge (b \vee \mathbf{F}c) \mathbf{U} \mathbf{G}b)$$

Correct because $\neg \mathbf{GF}c$
holds at some moment
iff it holds at every moment!



... et voilà!

$$\mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c)) \equiv \mathbf{G}c \wedge \mathbf{F}a \vee \mathbf{F}(a \wedge (b \vee \mathbf{F}c)\mathbf{U} \mathbf{G}b)$$

Demystifying normalization

$$\mathbf{F} \left(a \wedge \mathbf{G} \left(b \vee \mathbf{F}(c \wedge \mathbf{G}d) \right) \right)$$

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$$\begin{aligned} & \mathbf{F} \left(a \wedge \mathbf{G} \left(b \vee \mathbf{F}(c \wedge \mathbf{G}d) \right) \right) \\ \equiv & \mathbf{F}\mathbf{G}d \wedge \mathbf{F} \left(a \wedge \mathbf{G} \left(b \vee \mathbf{F}(c \wedge \mathbf{G}d) \right) \right) \\ & \vee \\ & \neg \mathbf{F}\mathbf{G}d \wedge \mathbf{F} \left(a \wedge \mathbf{G} \left(b \vee \mathbf{F}(c \wedge \mathbf{G}d) \right) \right) \end{aligned}$$

Demystifying normalization

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Demystifying normalization

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Demystifying normalization

$$\mathbf{F} \left(a \wedge \mathbf{G} \left(b \vee \mathbf{F}(c \wedge \mathbf{G}d) \right) \right)$$

$$\equiv \mathbf{F}\mathbf{G}d \wedge \left(\begin{array}{c} \mathbf{G}\mathbf{F}c \wedge \mathbf{F}(a \wedge \mathbf{true}) \\ \vee \\ \mathbf{F}\mathbf{G}\neg c \wedge \mathbf{F} \left(a \wedge \mathbf{F}(c \wedge \mathbf{G}d) \mathbf{U} \mathbf{G}(b \vee (c \wedge \mathbf{G}d)) \right) \end{array} \right)$$

\vee

$$\mathbf{G}\mathbf{F}\neg d \wedge \mathbf{F}(a \wedge \mathbf{G}b)$$

... et voilà!

$$\mathbf{F} \left(a \wedge \mathbf{G} \left(b \vee \mathbf{F}(c \wedge \mathbf{G}d) \right) \right)$$

$$\equiv \mathbf{F}\mathbf{G}d \wedge \mathbf{G}\mathbf{F}c \wedge \mathbf{F}a$$

\vee

$$\mathbf{F}\mathbf{G}d \wedge \mathbf{F} \left(a \wedge \mathbf{F}(c \wedge \mathbf{G}d) \mathbf{U} \mathbf{G} \left(b \vee (c \wedge \mathbf{G}d) \right) \right)$$

\vee

$$\mathbf{F}(a \wedge \mathbf{G}b)$$

Closed-form expression

$$\varphi \equiv \bigvee_{\substack{M \subseteq \mathbf{U}(\varphi) \\ N \subseteq \mathbf{W}(\varphi)}} \left(\varphi' \wedge \bigwedge_{\psi \in M} \mathbf{GF} \psi' \wedge \bigwedge_{\chi \in N} \mathbf{FG} \chi' \right)$$

Sickert and Esparza, LICS 2020

Esparza, Křetínský, and Sickert, JACM 2020

Closed-form expression

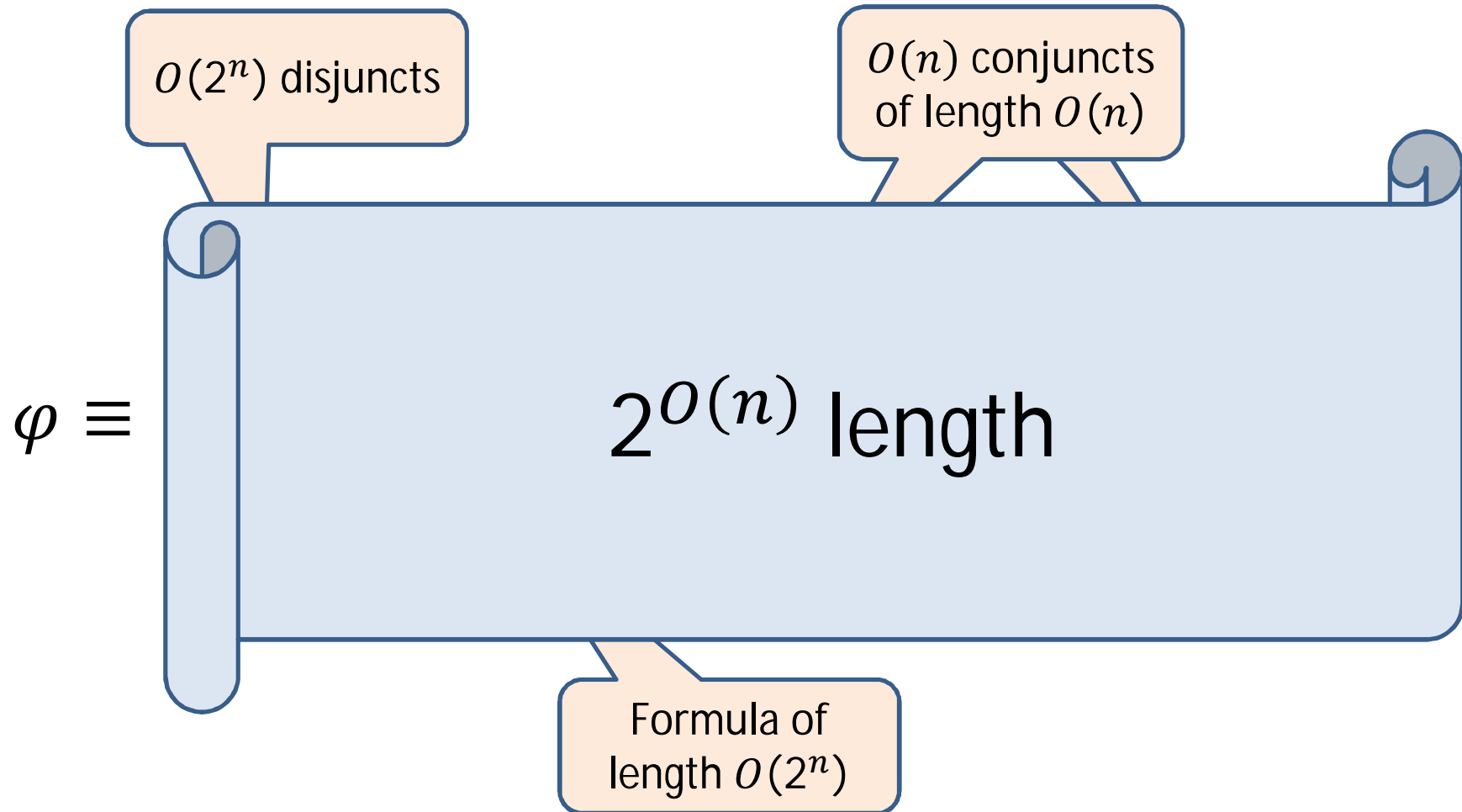
$O(2^n)$ disjuncts

$O(n)$ conjuncts of length $O(n)$

$$\varphi \equiv \bigvee_{\substack{M \subseteq \mathbf{U}(\varphi) \\ N \subseteq \mathbf{W}(\varphi)}} \left(\varphi' \wedge \bigwedge_{\psi \in M} \mathbf{GF} \psi' \wedge \bigwedge_{\chi \in N} \mathbf{FG} \chi' \right)$$

Formula of length $O(2^n)$

Closed-form expression



Sickert and Esparza, LICS 2020

Esparza, Křetínský, and Sickert, JACM 2020

Back from the past



LTL \Rightarrow Limit-deterministic Büchi automata



The Complexity of Probabilistic Verification

COSTAS COURCOUBETIS

University of Crete, and ICS, Farth, Heraklion, Greece

AND

MIHALIS YANNAKAKIS

AT&T Bell Laboratories, Murray Hill, New Jersey



1995: Limit-determinization procedure for ω -automata

LTL \Rightarrow Limit-deterministic Büchi automata



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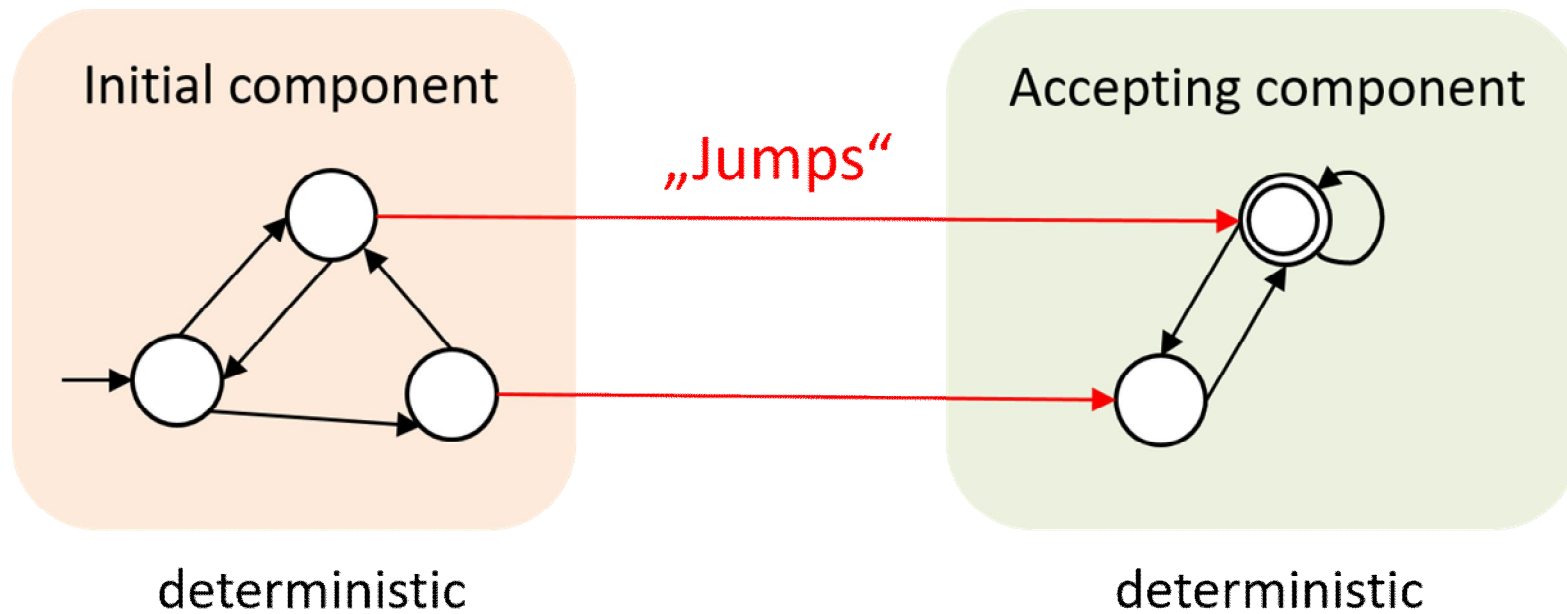
Formula

\Rightarrow Δ_2 -formula

\Rightarrow Limit-deterministic
Büchi automaton



LTL \Rightarrow Limit-deterministic Büchi automata



LTL \Rightarrow Limit-deterministic Büchi automata

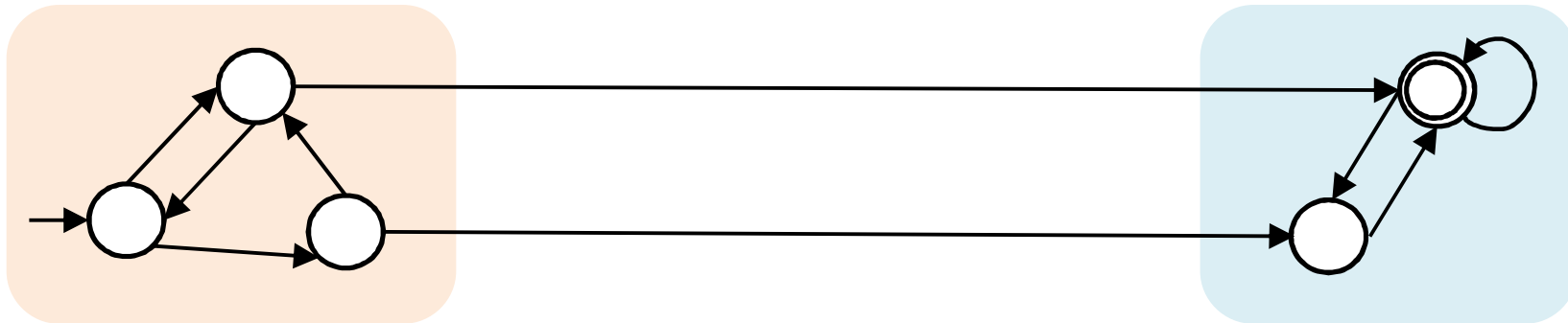
$$\mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c))$$

LTL \Rightarrow Limit-deterministic Büchi automata

$$\begin{aligned} & \mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c)) \\ & \quad \equiv \\ & (\mathbf{G}c \wedge \mathbf{F}a) \vee \mathbf{F}(a \wedge (b \vee \mathbf{F}c) \mathbf{U} \mathbf{G}b) \end{aligned}$$

LTL \Rightarrow Limit-deterministic Büchi automata

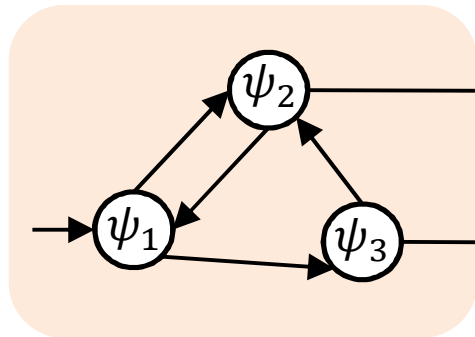
$$\begin{aligned} & \mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c)) \\ & \equiv \\ & (\mathbf{G}c \wedge \mathbf{F}a) \vee \mathbf{F}(a \wedge (b \vee \mathbf{F}c) \mathbf{U} \mathbf{G}b) \end{aligned}$$



LTL \Rightarrow Limit-deterministic Büchi automata

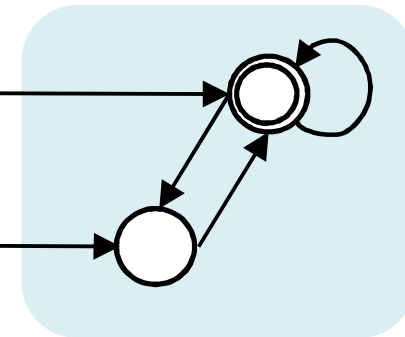
$$\mathbf{F}(a \wedge \mathbf{G}(b \vee \mathbf{F}c))$$
$$\equiv$$
$$(\mathbf{G}\mathbf{F}c \wedge \mathbf{F}a) \vee \mathbf{F}(a \wedge (b \vee \mathbf{F}c) \mathbf{U} \mathbf{G}b)$$

Maintains the formula
 ψ_i that must hold when
 $\mathbf{G}b$ starts to hold



Guesses the point at
which $\mathbf{G}b$ starts to hold

Checks
 $\psi_i \wedge \mathbf{G}b$



Size reduction

$$\bigwedge_{i=1}^j (\mathbf{GF}a_i) \implies \bigwedge_{i=1}^j (\mathbf{GF}b_i)$$

$$k: \bigwedge_{i=1}^k (\mathbf{GF}a_i \vee \mathbf{FG}b_i)$$

$$f(0, j) = (\mathbf{GF}a_0) \mathbf{U}(\mathbf{X}^j b)$$

$$f(i+1, j) = (\mathbf{GF}a_{i+1}) \mathbf{U}(\mathbf{G}f(i, j))$$

	LDBA	Safra (spot+Itl2dstar)
$j = 1$	3	5
$j = 2$	4	17
$j = 3$	5	49
$j = 4$	6	129
<hr/>		
$k = 2$	5	4385
$k = 3$	9	*
<hr/>		
$f(0, 0)$	5	5
$f(0, 2)$	10	10
$f(0, 4)$	16	12
$f(1, 0)$	6	196
$f(1, 2)$	28	109839
$f(1, 4)$	58	*
$f(2, 0)$	10	99793
$f(2, 2)$	46	*
$f(2, 4)$	92	*

LTL \Rightarrow deterministic Rabin automata



On The Complexity of ω -Automata*

Shmuel Safra

Department of Applied Mathematics
Weizmann Institute of Science
Rehovot 76100, Israel



1988: Determinization procedure for ω -automata

LTL \Rightarrow deterministic Rabin automata



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1988: Determinization procedure for ω -automata

Formula

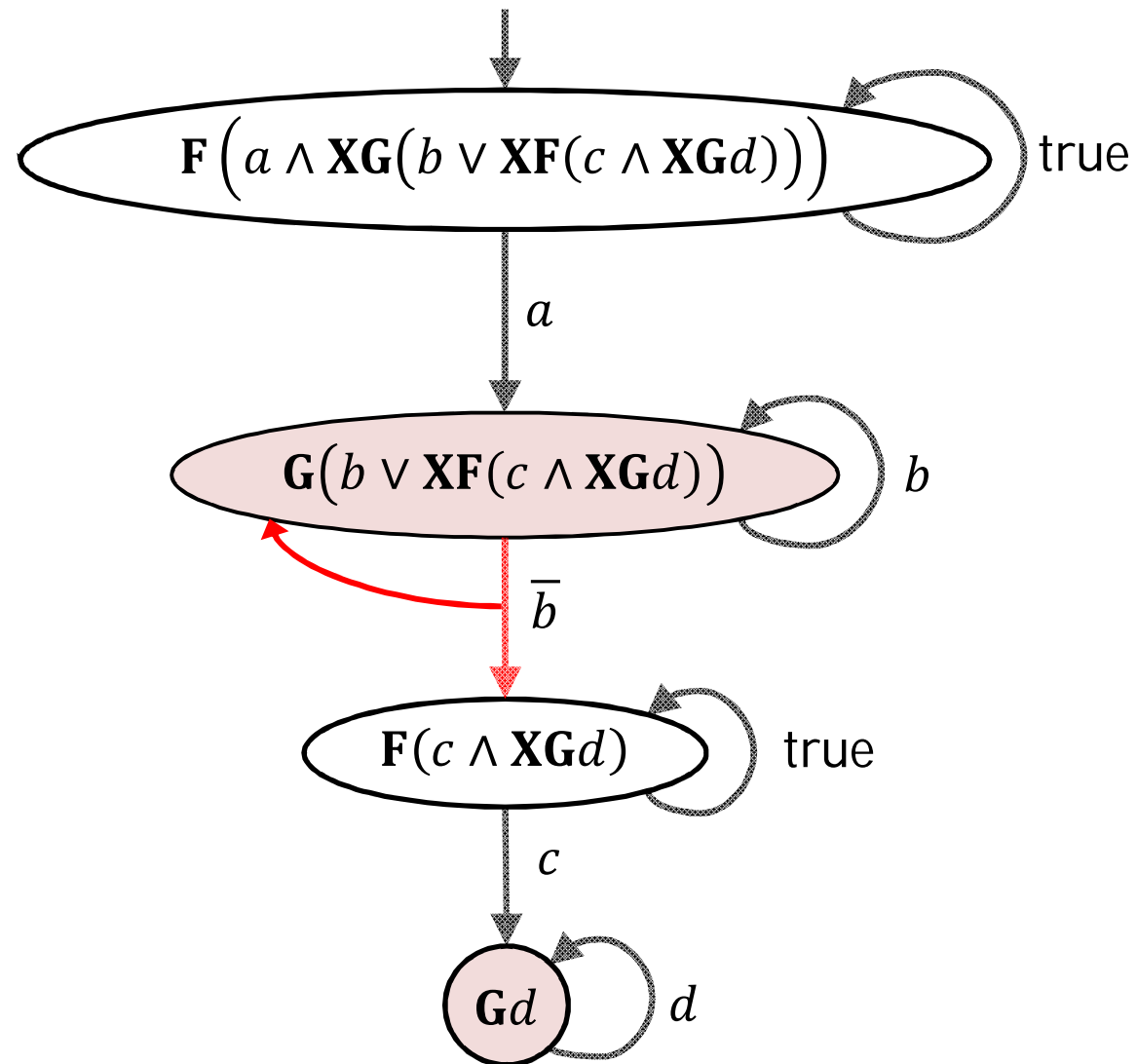
\Rightarrow Δ_2 -formula

\Rightarrow very weak Δ_2 -alternating
Büchi automaton

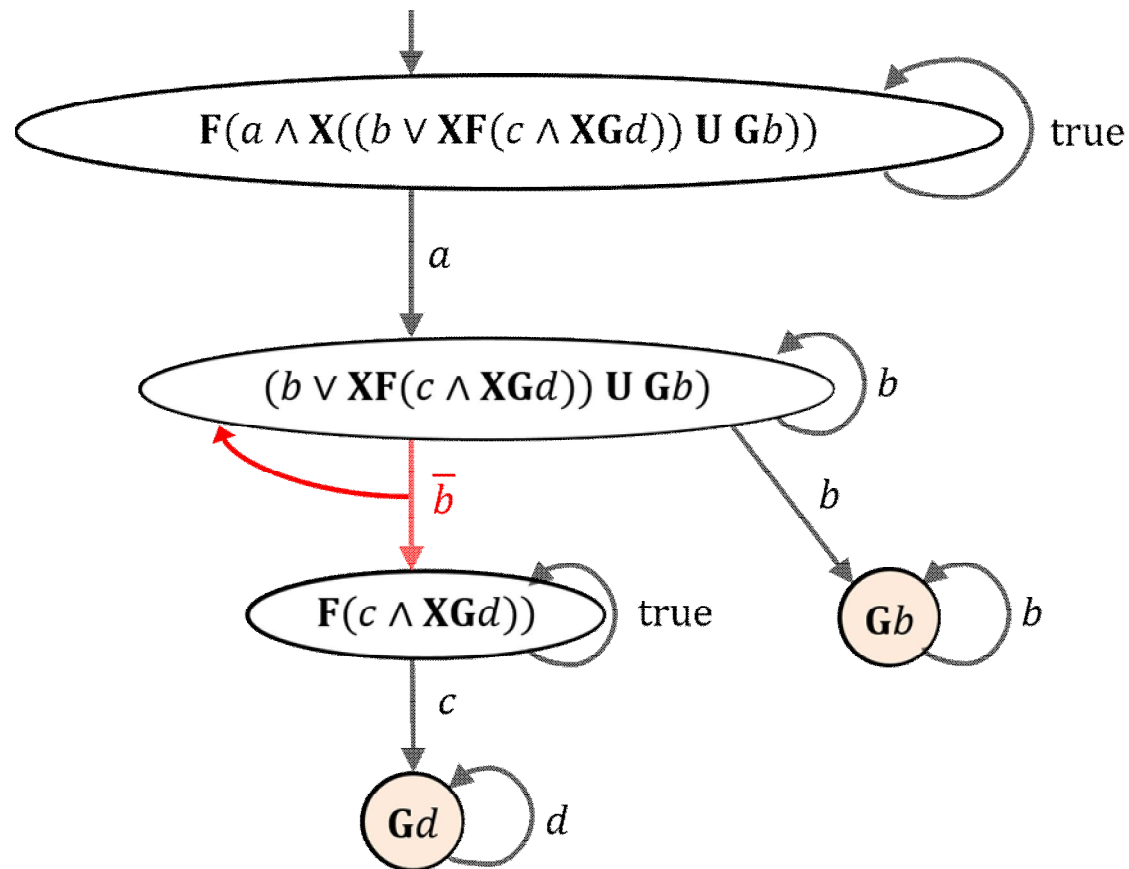
\Rightarrow deterministic Rabin automaton



From LTL to very weak alternating Büchi automata

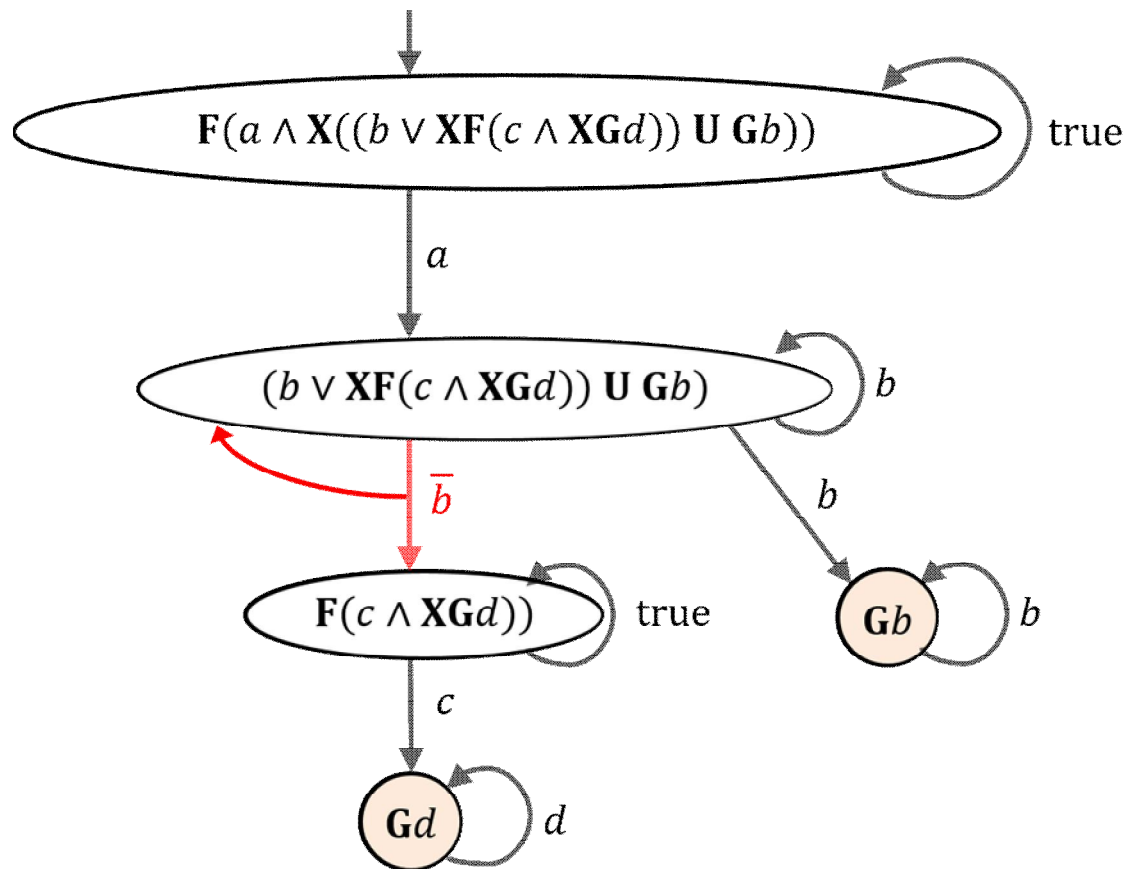


After Δ_2 -normalization



Disjunction of VWAA with $O(n)$ states s.t. each path has **only one alternation** between accepting and non-accepting states

After Δ_2 -normalization



Lemma: A Δ_2 -VWAA

accepts a word iff it has a run on it such that

- No level of the tree is (equiv. to) false, and
- All states of some level are accepting.

Equivalent deterministic Büchi or co-Büchi automaton using (a slight reformulation of) the **breakpoint construction**.

From trees of sets to pairs of sets.

Owl (owl.model.in.tum.de)

Owl

A Java tool collection and library for **O**mega-**w**ords, ω -automata and **L**inear Temporal Logic (LTL). Batteries included.



Online
Demo

Download
ZIP File

View On
GitLab

Owl is a Java 11 tool collection and library for ω -words, ω -automata and linear temporal logic. It provides a wide range of algorithms for automata and LTL. It has

Strix (strix.model.in.tum.de)

Tool for reactive LTL synthesis

- direct translation LTL-to-DPA
- multi-threaded, explicit-state solver for parity games.

Winner of the SYNTCOMP competition in 2018,2019, 2020

State-of-the-art in reactive LTL synthesis

Luttenberger, Meyer, Sickert,
CAV 2018 and Acta Informatica 2020

Assumptions:

```
1 true
```

Guarantees:

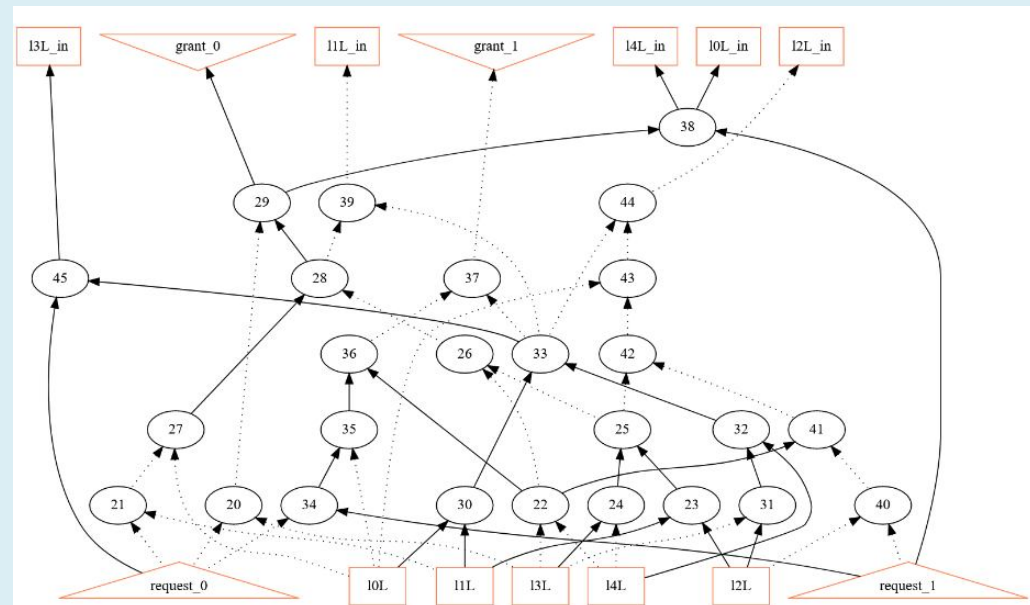
```
1 G (request_0 -> F grant_0)
2 G (request_1 -> F grant_1)
3 G (!grant_0 || !grant_1)
4 (!grant_0 & !request_0) W request_0
5 (!grant_1 & !request_1) W request_1
```

Input propositions:

```
request_0, request_1
```

Output propositions:

```
grant_0, grant_1
```



A fresh look at LTL

A fresh look at LTL

Imagine SAT without CNF

A fresh look at LTL

Imagine SAT without CNF

Imagine FOL without skolemization

A fresh look at LTL

Imagine SAT without CNF

Imagine FOL without skolemization

That's what happened to LTL

Thank you for your attention!



Thank you for your attention!